# Algorithms and datastructures I Lecture 9: RB-trees and hashing 

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## Set datastructure

We would like to represent a set (or a dictionary) of some elements from an universe.
We expect that elements of the universum in set can be assigned and compared in $O(1)$.
InSERT( $v$ ): Insert $v$ to the set.
$\operatorname{Delete}(v)$ : Delete $v$ from the set.
$\operatorname{FiND}(v)$ : Find $v$ in the set.
MIN: Return minimum.
MAX: Return maximum.
Succ(v): Find successor.
$\operatorname{Pred}(v)$ : Find predecessor.

## Basic implementations

|  | INSERT | DELETE | FIND | Min/MAX | SUCC/PRED |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Linked list | $O(n)$ or $O(1)$ | $O(n)$ or $O(1)$ | $O(n)$ | $O(n)$ | $O(n)$ |
| Array | $O(n)$ or $O(1)$ | $O(n)$ or $O(1)$ | $O(n)$ | $O(n)$ | $O(n)$ |
| Sorted array | $O(n)$ | $O(n)$ | $O(\log n)$ | $O(1)$ | $O(\log n)$ or $O(1)$ |
| binary search trees | $O(n)$ | $O(n)$ | $O(n)$ | $O(n)$ | $O(n)$ |
| AVL-trees | $O(\log n)$ | $O(\log n)$ | $O(\log n)$ | $O(\log n)$ | $O(\log n)$ |
| $(r, b)$ trees | $O(\log n)$ | $O(\log n)$ | $O(\log n)$ | $O(\log n)$ | $O(\log n)$ |

## (a, b)-trees (Bayer, McCreight)



Rudolf Bayer


Edward M. McCreight

## Definition (Generalized search tree)

Generalised search tree is a rooted tree with specified order of sons and two types of vertices:

1. Internal vertices contains non-zero number of keys. If internal vertex has keys $x_{1}<\cdots<x_{k}$ then it has $k+1$ sons $s_{0}, \ldots, s_{k}$. Keys separate values in sons, so:

$$
T\left(s_{0}\right)<x_{1}<T\left(s_{1}\right)<x_{2}<\cdots<x_{k-1}<T\left(s_{k-1}\right)<x_{k}<T\left(s_{k}\right)
$$

2. External vertices contain no keys and are leaf.

Definition ((a, b)-tree)
$(a, b)$-tree for a given $a \geq 2, b \geq 2 a-1$ is a generalised search tree such that:

1. Root has 2 to $b$ sons.
2. Other internal vertices have $a$ to $b$ sons.
3. All external vertices are in the level.

## Lemma

Every $(a, b)$-tree with $n$ keys has depth $\Theta(\log n)$.

Insert to ( $a, b$ )-tree

## Insert( $v, x$ )

Let $u$ be the last internal vertex visited by $\operatorname{Find}(v, x)$.

1. If $u$ contains $x$ return.
2. Otherwise add $x$ into $u$ and insert new external vertex
3. If $u$ has more than $b$ sons, split it possibly recursing to father.

It is possible to split preventively if $b \geq 2 a$. We will use it today.

## Red-black trees (Bayer 1972; Guibas, Sedgewick 1978; Anderson 1993; Sedgewick 2008)

We can represent $(2,4)$-trees using binary search trees with colored edges.


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Robert Sedgewick

## Definition (Left leaning red-back tree)

LLRB-tree is binary search tree with external vertices and edges colored either red or black. It satisfies:

1. There are no two red edges adjacent to each other.
2. If there is only one red edge from a vertex then it is left.
3. Edges to leaves are always black.
4. Every path from root to leaf goes through the same number of black edges.

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Optimization: Color of edge may be stored in its destination vertex.

## Depth of LLRB-trees

## Lemma

Every LLRB-tree with $n$ keys has depth $\Theta(\log n)$.

## Proof.

We know that every LLRB-tree tree corresponds to an (2,4)-tree of height $h=\Theta(\log n)$.
The height $h^{\prime}$ of LLRB tree is $h \leq h^{\prime} \leq 2 h$.

## Operations on LLRB-trees

## Observation

Operations Find, Min, Max, Succ and Pred run in $\Theta(\log n)$.

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Operations Find, Min, Max, Succ and Pred run in $\Theta(\log n)$.
Operations Insert and Delete can be derived from ones on (2, 4)-trees.

## INSERT to an LLRB-tree

Lets see how insertion to (2, 4)-tree with preventive splitting translates to RB-tree.
Insert( $v, x$ )

1. If $v=\emptyset$ : return newly created red vertex with key $x$.
2. If $x=k(v)$ : Return $v$.

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## $\operatorname{Insert}(v, x)$

1. If $v=\emptyset$ : return newly created red vertex with key $x$.
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3. If $I(v)$ and $r(v)$ are red: change color of $v, I(v)$ and $r(v)$.

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3. If $I(v)$ and $r(v)$ are red: change color of $v, I(v)$ and $r(v)$.
4. If $x<k(v): I(v) \leftarrow \operatorname{Insert}(I(v), x)$.
5. If $x>k(v): r(v) \leftarrow \operatorname{lnsert}(r(v), x)$.

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7. If $I(v)$ and $I(I(v))$ are red: rotate edge $(v, I(v))$ and put to $v$ original $I(v)$.

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Exchanging steps 3 and 7 leads to representation of (2,3)-trees.

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Fact: Delete can also be implemented in $\Theta(\log n)$ time.

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Exchanging steps 3 and 7 leads to representation of (2,3)-trees.
Fact: Delete can also be implemented in $\Theta(\log n)$ time.

## Theorem

Operations Insert, Delete, Find, Min, Max, Succ and Pred on LLRB-tree runs in $\Theta(\log n)$ time.


## Tries

Let $\Sigma$ be a fixed alphabet. Let $S \subseteq \Sigma^{*}$ be a set of words over alphabet $\Sigma$.
Definition (Trie: middle of retrieval, invented by René de la Briandais in 1959; named by Edward Frenklin)
Trie for some set of words $S$ is a rooted tree where

1. vertices are all prefixes of words $W \in X$, and
2. $W^{\prime}$ is a son of word $W$ if $W^{\prime}$ is created from $W$ by extending it by one letter.

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## Theorem

Find, Insert and Delete for word $X$ can all be implemented in $O(|X|)$.
To store sets of integers one can see integers as words in some fixed base. Result is known as a radix tree.

## Amortised complexity

Insertion to a (dynamically allocated) growing array.
Insert( $(A, s, n), x)$ insert element $x$ to array $A$ of size $s$ containing $n$ elements

1. if $n=s$ :
2. Allocate array $A^{\prime}$ of size 2 s .
3. For $i=0,1, \ldots, n-1: A^{\prime}[i] \leftarrow A[i]$.
4. Free $A$.
5. $A \leftarrow A^{\prime}, s \leftarrow 2 s$
6. $A[n] \leftarrow x, n \leftarrow n+1$
7. Return $(A, s, n)$.

Worst case complexity of INSERT is $O(n)$.

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Worst case complexity of INSERT is $O(n)$.

## Theorem

Performing $n$ operations INSERT starting from the empty array will run in time $\Theta(n)$.

## Proof.

To insert $2^{i}$ elements one needs $2^{0}+2^{1}+2^{2}+2^{3}+\cdots+2^{i-1}=2^{i}-1$ copy operations.

## Hash functions

Hash function is a function $h$ from universe $\mathcal{U}$ to set $\mathcal{P}=\{0,1, \ldots, p-1\}$ (of hashes).
Hash table with separate chaining for set $S \subseteq U$ with hash function $h: \mathcal{U} \rightarrow \mathcal{P}$.
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## Corollary

Putting $p \sim|S|$ we get FIND, INSERT and DELETE is running on average approximately in $O(1)$.

## Hash functions

Example (Integers: $h: \mathbb{N} \rightarrow\{0,1, \ldots, p-1\}$ )

$$
h(x)=a x \bmod p
$$

where $a, p$ are prime numbers.

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Example (Strings: $\left.h: \mathbb{N}^{*} \rightarrow\{0,1, \ldots, p-1\}\right)$

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h(x)=\left(\begin{array}{ll}
\sum_{i=1}^{|x|} x_{i} a^{|x|-i} & \bmod p
\end{array}\right)
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## Example (Strings: $h: \mathbb{N}^{*} \rightarrow\{0,1, \ldots, p-1\}$ )

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h(x)=\left(\sum_{i=1}^{|x|} x_{i} a^{|x|-i} \bmod p\right)
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Can be effectively computed as (Horner's method):

$$
\begin{aligned}
h_{1} & =x_{1} \\
h_{2} & =\left(h_{1} a+x_{2}\right) \bmod p \\
h_{3} & =\left(h_{2} a+x_{3}\right) \bmod p \\
\ldots & \cdots \\
h_{|x|} & =\left(h_{|x|-1} a+x_{|x|}\right) \bmod p
\end{aligned}
$$

## Open addressing

An alternative way of solving collisions is to use hash function $h(x, i)$ such that for every $x \in \mathcal{U}$ sequence $h(x, 0), h(x, 1), \ldots, h(x, p-1)$ is a permutation of $(0,1, \ldots, p-1)$.

## Insert(x)

1. For $i=0, \ldots, p-1$ :
2. $j \leftarrow h(x, i)$
3. If $H[j]=\emptyset:$ put $H[j] \leftarrow x$ and return.
4. Report that table is full.

## Find $(x)$

1. For $i=0, \ldots, p-1$ :
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We can not remove values from the table, just mark them as removed.

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## Find ( x )

1. For $i=0, \ldots, p-1$ :
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## Theorem

Assuming that the hash function is giving random permutations, the average number of visited entries during unsuccessful find is $\frac{1}{(1-\alpha)}$ for $\alpha=\frac{n}{m}$.

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Let $p_{i}$ be probability that we will search at least $i$ entries. $p_{1}=1, p_{2}=\frac{n}{m}=\alpha, p_{3}=\alpha \frac{n-1}{m-1} \leq \alpha^{2}, \ldots$.

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Universal hashing

## Definition ( $c$-universal system of hash functions)

System $\mathcal{S}$ of hash functions from universe $\mathcal{U}$ to $\{0,1, \ldots, p-1\}$ is $c$-universal for given $c \geq 1$ if for every $x, y \in \mathcal{U}, x \neq y$

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1-universal system

## System of functions $\mathcal{S}: \mathbb{Z}_{p}^{d} \rightarrow\{0,1, \ldots, p-1\}$

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$\sum_{i=1}^{d-1} a_{i} z_{i}+a_{d} z_{d} \equiv 0$ happens only if $\sum_{i=1}^{d-1} a_{i} z_{i} \equiv-a_{d} z_{d}$. This has probability $\frac{1}{p}$.

