Algorithms and datastructures I Lecture 9: RB-trees and hashing

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Set datastructure

We would like to represent a set (or a dictionary) of some elements from an universe. We expect that elements of the universum in set can be assigned and compared in O(1).

INSERT(v): Insert v to the set.

DELETE(v): Delete v from the set.

FIND(v): Find v in the set.

MIN: Return minimum.

Max: Return maximum.

Succ(v): Find successor.

PRED(v): Find predecessor.

Basic implementations					
	INSERT	DELETE	FIND	MIN/MAX	Succ/Pred
Linked list	<i>O</i> (<i>n</i>) or <i>O</i> (1)	O(n) or O(1)	O(n)	O(n)	O(n)
Array	O(n) or $O(1)$	O(n) or $O(1)$	O(n)	O(n)	O(n)
Sorted array	O(n)	O(n)	$O(\log n)$	<i>O</i> (1)	$O(\log n)$ or $O(1)$
binary search trees	O(n)	O(n)	O(n)	O(n)	O(n)
AVL-trees	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(\log n)$
(r, b)-trees	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(\log n)$

(a, b)-trees (Bayer, McCreight)





Rudolf Bayer

M. McCreight

Definition (Generalized search tree)

Generalised search tree is a rooted tree with specified order of sons and two types of vertices:

1. Internal vertices contains non-zero number of keys. If internal vertex has keys $x_1 < \cdots < x_k$ then it has k+1 sons s_0, \ldots, s_k . Keys separate values in sons, so:

$$T(s_0) < x_1 < T(s_1) < x_2 < \cdots < x_{k-1} < T(s_{k-1}) < x_k < T(s_k)$$

2. External vertices contain no keys and are leaf.

Definition ((a, b)-tree)

(a, b)-tree for a given $a \ge 2$, $b \ge 2a - 1$ is a generalised search tree such that:

- 1. Root has 2 to b sons.
- 2. Other internal vertices have a to b sons.
- 3. All external vertices are in the level.

Lemma

Every (a, b)-tree with n keys has depth $\Theta(\log n)$.

Insert to (a, b)-tree

Insert(v,x)

Let u be the last internal vertex visited by Find(v,x).

- 1. If *u* contains *x* return.
- 2. Otherwise add x into u and insert new external vertex
- 3. If *u* has more than *b* sons, split it possibly recursing to father.

It is possible to split preventively if $b \ge 2a$. We will use it today.

We can represent (2, 4)-trees using binary search trees with colored edges.



Leonidas J. Guibas



Robert Sedgewick

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Definition (Left leaning red-back tree)

LLRB-tree is binary search tree with external vertices and edges colored either red or black. It satisfies:

- 1. There are no two red edges adjacent to each other.
- 2. If there is only one red edge from a vertex then it is left.
- 3. Edges to leaves are always black.
- 4. Every path from root to leaf goes through the same number of black edges.

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Optimization: Color of edge may be stored in its destination vertex.

Depth of LLRB-trees

Lemma

Every LLRB-tree with n keys has depth $\Theta(\log n)$.

Proof.

We know that every LLRB-tree tree corresponds to an (2,4)-tree of height $h = \Theta(\log n)$. The height h' of LLRB tree is $h \le h' \le 2h$.

Operations on LLRB-trees

Observation

Operations FIND, MIN, MAX, SUCC and PRED run in $\Theta(\log n)$.

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Operations INSERT and DELETE can be derived from ones on (2, 4)-trees.

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- 8. Return v.

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Exchanging steps 3 and 7 leads to representation of (2, 3)-trees.

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- 6. If I(v) is black and r(v) red: rotate edge (v, r(v)) and put to v original r(v).
- 7. If I(v) and I(I(v)) are red: rotate edge (v, I(v)) and put to v original I(v).
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Fact: DELETE can also be implemented in $\Theta(\log n)$ time.

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Exchanging steps 3 and 7 leads to representation of (2, 3)-trees.

Fact: Delete can also be implemented in $\Theta(\log n)$ time.

Theorem

Operations INSERT, DELETE, FIND, MIN, MAX, SUCC and PRED on LLRB-tree runs in $\Theta(\log n)$ time.



Tries

Let Σ be a fixed alphabet. Let $S \subset \Sigma^*$ be a set of words over alphabet Σ .

Definition (Trie: middle of retrieval, invented by René de la Briandais in 1959; named by Edward Frenklin)

Trie for some set of words S is a rooted tree where

- 1. vertices are all prefixes of words $W \in X$, and
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To store sets of integers one can see integers as words in some fixed base. Result is known as a radix tree.

Amortised complexity

Insertion to a (dynamically allocated) growing array.

Insert((A, s, n), x) insert element x to array A of size s containing n elements

- 1. if n = s:
- 2. Allocate array A' of size 2s.
- 3. For i = 0, 1, ..., n-1: $A'[i] \leftarrow A[i]$.
- 4. Free A.
- 5. $A \leftarrow A', s \leftarrow 2s$
- 6. $A[n] \leftarrow x, n \leftarrow n + 1$
- 7. Return (A, s, n).

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- 7. Return (A, s, n).

Worst case complexity of INSERT is O(n).

Theorem

Performing n operations INSERT starting from the empty array will run in time $\Theta(n)$.

Proof.

To insert 2^i elements one needs $2^0 + 2^1 + 2^2 + 2^3 + \cdots + 2^{i-1} = 2^i - 1$ copy operations.

Hash function is a function *h* from universe \mathcal{U} to set $\mathcal{P} = \{0, 1, \dots, p-1\}$ (of hashes).

Hash table with separate chaining for set $S \subseteq U$ with hash function $h: \mathcal{U} \to \mathcal{P}$.

Hash table is an array H of linked lists indexed by \mathcal{P} . List H[i] contains all elements e of set S such that h(e) = i.

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Assumptions

- 1. h(x) can be computed in O(1).
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Putting $p \sim |S|$ we get FIND, INSERT and DELETE is running on average approximately in O(1).

Example (Integers:
$$h: \mathbb{N} \to \{0, 1, \dots, p-1\}$$
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$$h(x) = \left(\sum_{i=1}^{|x|} x_i a^{|x|-i} \mod p\right).$$

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Can be effectively computed as (Horner's method):

$$h_1 = x_1$$
 $h_2 = (h_1 a + x_2) \mod p$
 $h_3 = (h_2 a + x_3) \mod p$
 \dots
 $h_{|X|} = (h_{|X|-1} a + x_{|X|}) \mod p$

Open addressing

An alternative way of solving collisions is to use hash function h(x, i) such that for every $x \in \mathcal{U}$ sequence $h(x, 0), h(x, 1), \dots, h(x, p - 1)$ is a permutation of $(0, 1, \dots, p - 1)$.

Insert(x)

- 1. For i = 0, ..., p 1:
- 2. $j \leftarrow h(x, i)$
- 3. If $H[j] = \emptyset$: put $H[j] \leftarrow x$ and return.
- 4. Report that table is full.

Find(x)

- 1. For i = 0, ..., p-1:
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We can not remove values from the table, just mark them as removed.

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Proof.

$$S = \sum_{i>1} i(p_i - p_{i+1}) = \sum_{i>1} (i - (i-1))p_i = \sum_{i>1} p_i \le \sum_{i>1} \alpha^{i-1}$$

An alternative way of solving collisions is to use hash function h(x, i) such that for every $x \in \mathcal{U}$ sequence $h(x, 0), h(x, 1), \dots, h(x, p - 1)$ is a permutation of $(0, 1, \dots, p - 1)$.

Insert(x)

- 1. For i = 0, ..., p 1:
- 2. $j \leftarrow h(x, i)$
- 3. If $H[j] = \emptyset$: put $H[j] \leftarrow x$ and return.
- 4. Report that table is full.

Find(x)

- 1. For i = 0, ..., p-1:
- 2. $j \leftarrow h(x, i)$
- 3. If H[j] = x: return j.
- 4. Return Ø.

Theorem

Assuming that the hash function is giving random permutations, the average number of visited entries during unsuccessful find is $\frac{1}{(1-\alpha)}$ for $\alpha=\frac{n}{m}$.

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- 4. Return 0.

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Double hashing: $h(x, i) = (f(x) + i(g(x) + 1)) \mod m$ for f and g being two different hash functions.

Definition (*c*-universal system of hash functions)

System $\mathcal S$ of hash functions from universe $\mathcal U$ to $\{0,1,\ldots,p-1\}$ is c-universal for given $c\geq 1$ if for every $x,y\in \mathcal U, x\neq y$

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Let S be c-universal system of hash functions $\mathcal{U} \to \{0, 1, \dots, p\}$. Let x_1, x_2, \dots, x_n, y be pairwise different elements of \mathcal{U} . Then

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System of functions $S: \mathbb{Z}_p^d \to \{0, 1, \dots, p-1\}$

Let p be a prime number, $\mathcal{P}=\mathbb{Z}_p$ (ring modulo p), $\mathcal{U}=\mathbb{Z}_p^d$ (vectors of length d in \mathbb{Z}_p).

$$S = \{h_{\vec{a}} \colon \vec{a} \in \mathbb{Z}_p^d, \vec{a} \neq 0\}$$
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$$\sum_{i=1}^{d-1} a_i z_i + a_d z_d \equiv 0$$
 happens only if $\sum_{i=1}^{d-1} a_i z_i \equiv -a_d z_d$. This has probability $\frac{1}{p}$.