

- Commonly known Rayleigh-Ritz method for the discrete spectrum

$$[E] = \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle}$$

- The energy is prescribed for the continuum states
- RR method gives an approximation for ψ and for E
- Variational principles do not provide eigenstates and eigenenergies, just their approximations
- Why VP's then?

1.) Kohn & Nishitani

2.) Schwinger method

3.) R-matrix

① Kohn variational principle (initially by Hulthén 1944)

$$\underbrace{\left[-\frac{d^2}{dr^2} + \frac{l(l+1)}{r^2} + 2V(r) - k^2 \right]}_{L_l(E)} \mu_l(r) = 0$$

- Functional

$$I_l = \int_0^\infty \bar{\mu}_l(r) L_l(E) \mu_l(r) \dots \text{for } \overset{\text{real}}{\text{trial solutions}} \bar{\mu}_l(r)$$

A.) $\bar{\mu}_l(0) = 0$

B.) $\bar{\mu}_l(r) \xrightarrow{r \rightarrow \infty} F_l(kr) + \lambda G_l(kr) \dots$ $F_l(kr), G_l(kr)$ linearly independent free solutions for $V(r) = 0$

• Functional $I_l = 0$ for trial $\bar{\mu}_l = \mu_l$

- Plan variational

Variation of I_E around the exact solution, i.e. $\bar{u}_E(r) = u_E(r) + \delta u_E(r)$

(2)

A.) $\delta u_E(r) = 0$

B.) $\delta u_E(r) \xrightarrow{r \rightarrow \infty} \delta \lambda G_E(kr)$

$$\delta I_E = \int_0^a \delta u_E L_E u_E + \underbrace{\int_0^a u_E L_E \delta u_E}_{(A)} + \int_0^a \delta u_E L_E \delta u_E \quad ; \quad \boxed{W(F, G) = FG' - F'G}$$

(A) kinetic energy $-\frac{d^2}{dr^2}$ is a single non-symmetric (non-hermitian) operator on class of functions $u_E(r), \delta u_E(r)$

$$-\int_0^R u_E \frac{d^2}{dr^2} \delta u_E = -\left[u_E \frac{d}{dr} \delta u_E \right]_0^R + \int_0^R \frac{du_E}{dr} \frac{d\delta u_E}{dr} = -\left[u_E \frac{d}{dr} \delta u_E \right]_0^R + \left[\frac{du_E}{dr} \delta u_E \right]_0^R$$

$$-\int_0^R \frac{d\delta u_E}{dr} u_E = \left[\frac{d\delta u_E}{dr} u_E \right]_0^R - \int_0^R \delta u_E \frac{du_E}{dr}$$

$W(\delta u_E, u_E) \Big|_{R \rightarrow \infty} = \delta \lambda k W(G, F)$

$$\delta I_E = 2 \int_0^a \delta u_E L_E u_E + \delta \lambda k \underbrace{W(G, F)}_{-W(F, G) = -W} + \int_0^a \delta u_E L_E \delta u_E$$

$$\delta I_E = -\delta \lambda k W(F, G) + \int_0^a \delta u_E L_E \delta u_E \quad \text{Kato identity}$$

$$\boxed{[\lambda]} = \lambda + \frac{1}{kW} \int_0^a \bar{u}_E L_E \bar{u}_E \quad \text{General Kohn VP}$$

Choice of the asymptotics F_E, G_E :

1.) $F_E(kr) = \sin(kr - \frac{2\pi}{2})$
 $G_E(kr) = \cos(kr - \frac{2\pi}{2})$

$u_E(r) \xrightarrow{r \rightarrow \infty} \sin(kr - \frac{2\pi}{2}) + \cos(kr - \frac{2\pi}{2})$

$$\boxed{W(F_E, G_E) = -1} \quad \lambda = \text{tg} \delta_E \quad \left[\text{tg} \delta_E \right] = \text{tg} \delta_E - \frac{1}{k} \int_0^a \bar{u}_E L_E \bar{u}_E \quad \text{Kohn}$$

2.) $F_E(kr) = \cos(kr - \frac{2\pi}{2})$
 $G_E(kr) = \sin(kr - \frac{2\pi}{2})$

$$\boxed{W(F_E, G_E) = +1} \quad \lambda = \text{cotg} \delta_E \quad \left[\text{cotg} \delta_E \right] = \text{cotg} \delta_E + \frac{1}{k} \int_0^a \bar{u}_E L_E \bar{u}_E \quad \text{Rubinow (Inverse Kohn VP)}$$

3.) Whole procedure needs to be repeated

$u_E(r) \xrightarrow{r \rightarrow \infty} \sin(kr - \frac{2\pi}{2} + \delta) \quad [\delta_E] = \delta_E + \frac{1}{k} \int_0^a \bar{u}_E L_E \bar{u}_E \quad \text{Hulthén}$

Kohn variational method: solution in a basis

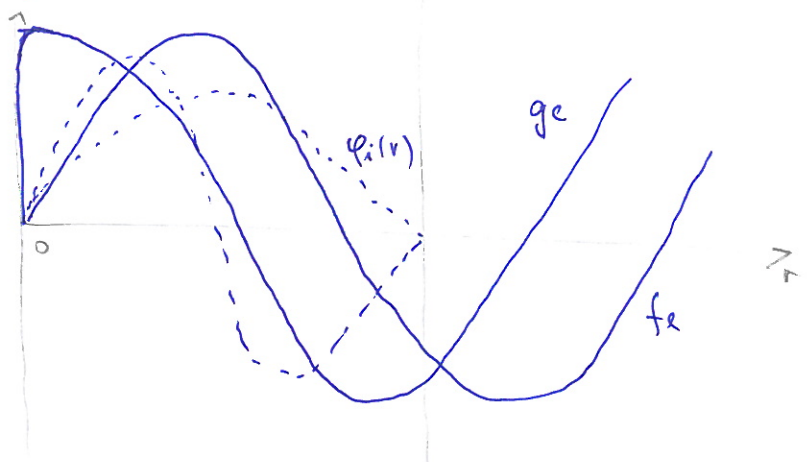
- Assume that $v(r)$ is negligible beyond R .

$\bar{u}_e(r) = f_e(kr) + \bar{\lambda} g_e(kr) + \sum_{i=1}^N c_i \varphi_i(r)$ basis consists of $N+2$ elements

A.) $\varphi_i(0) = 0$

B.) $\varphi_i(r) = 0$ for $r \geq R$

C.) $f_e(0) = g_e(0) = 0$



$[\lambda] = \bar{\lambda} + \frac{1}{k\omega} \int_0^{\infty} [f_e(kr) + \bar{\lambda} g_e(kr) + \sum_i c_i \varphi_i] L_e [f_e + \bar{\lambda} g_e + \sum_i c_i \varphi_i]$

Variations:

1.) $\frac{\partial [\lambda]}{\partial \bar{\lambda}} = 0 = 1 + \frac{1}{k\omega} \int_0^{\infty} g_e L_e \bar{u}_e + \frac{1}{k\omega} \int_0^{\infty} \bar{u}_e L_e g_e$
 $= 1 + \frac{2}{k\omega} \int_0^{\infty} g_e L_e \bar{u}_e + \frac{1}{k\omega} \underbrace{\omega(g_e, \bar{u}_e)}_{-\omega(f_e, g_e)} \Big|_{R \rightarrow \infty}$
 $\Rightarrow \int_0^{\infty} g_e L_e \bar{u}_e = 0$

2.) $\frac{\partial [\lambda]}{\partial c_j} = 0 \Rightarrow \int \varphi_j L_e \bar{u}_e = 0$ } $\left. \begin{matrix} \varphi_0 \equiv g_e \\ c_0 \equiv \bar{\lambda} \end{matrix} \right\}$ gives

$\rightarrow \int_0^{\infty} \varphi_j L_e (f_e + \sum_{i=0}^N c_i \varphi_i) = 0 \Rightarrow$

$$\underline{M} \underline{c} + \underline{S} = 0$$

$$\underline{c} = -\underline{M}^{-1} \underline{S}$$

M is energy dependent

$M_{ij} = \int_0^a \varphi_i L_e \varphi_j$

$S_i = \int_0^{\infty} \varphi_i L_e f_e$

- inversions cause kohn anomalies for real f_e and g_e

- Problem is solved for $g_e = i (F_e(kr) + i P_e(kr))$ - complex kohn method

② Schwinger variational principle

- Originated in Schwinger lectures at Harvard, published 1947
- Variational method based on L-S equation

Identities (we will work with the retarded Green's operator $G_0^{(+)}$)

$$\textcircled{A} \quad |k^{(+)}\rangle = |k\rangle + G_0^{(+)} V |k^{(+)}\rangle$$

$$\underline{|k^+\rangle = |k\rangle + G_0^{(+)} V |k^+\rangle}$$

$$\textcircled{B} \quad \underline{\langle k^-| = \langle k| + \langle k^-| V G_0^{(+)}}$$

$$\langle k^-| V \textcircled{A} \Rightarrow \langle k^-| V |k^+\rangle = \underbrace{\langle k^-| V |k\rangle}_{\langle k^-| T |k\rangle} + \langle k^-| V G_0^{(+)} V |k^+\rangle$$

$$\textcircled{C} \quad \underline{\langle k^-| T |k\rangle = \langle k^-| V - V G_0^{(+)} V |k^+\rangle}$$

$\rightarrow |k^+\rangle$ and $\langle k^-|$ are the exact solutions
 $\rightarrow \bar{|k^+\rangle}$ and $\langle \bar{k}^-|$ are the trial solutions

New identity from \textcircled{C} we have

$$\langle \bar{k}^-| T |k\rangle = \langle \bar{k}^-| - \bar{k}^-| V - V G_0^{(+)} V | \bar{k}^+ - k^+ \rangle - \langle \bar{k}^-| V - V G_0^{(+)} V | \bar{k}^+ \rangle +$$

$$+ \underbrace{\langle \bar{k}^-| V - V G_0^{(+)} V | k^+ \rangle}_{\textcircled{A} \quad V|k\rangle} + \underbrace{\langle \bar{k}^-| V - V G_0^{(+)} V | k^+ \rangle}_{\textcircled{B} \quad \langle \bar{k}^-| V}$$

Therefore:

$$\langle \bar{k}^-| T |k\rangle = \langle \bar{k}^-| V |k\rangle + \langle \bar{k}^-| V |k^+ \rangle - \langle \bar{k}^-| V - V G_0^{(+)} V | \bar{k}^+ \rangle + \langle \Delta \bar{k}^-| V - V G_0^{(+)} V | \Delta k^+ \rangle$$

Still an identity

$$\Delta k^+ = |\bar{k}^+ - k^+ \rangle$$

$$\Delta \bar{k}^- = \langle \bar{k}^- - k^- |$$

Let's assume $\langle \bar{k}^-|$ and $|\bar{k}^+\rangle$ are exact:

$$\langle \bar{k}^-| T |k\rangle = \langle \bar{k}^-| T |k\rangle + \langle \bar{k}^-| T |k\rangle - \langle \bar{k}^-| T |k\rangle + \phi$$

$$\boxed{[\langle \bar{k}^-| T |k\rangle] = \langle \bar{k}^-| V |k\rangle + \langle \bar{k}^-| V |k^+ \rangle - \langle \bar{k}^-| V - V G_0^{(+)} V | k^+ \rangle + \delta(\Delta \bar{k}^-)}$$

Linear form of the Schwinger variational principle

A note: Is it possible to form VP instead of $t = t+t-t$ in form of $t = \frac{t \cdot t}{t}$?

Is $\langle k' | T | k \rangle = \frac{\langle k' | V | \bar{k}^+ \rangle \langle \bar{k}^- | V | k \rangle}{\langle \bar{k}^- | V - V G_0^{(+)} V | \bar{k}^+ \rangle}$ variationally stable?

Substitutions in the Schwinger VP - stimulated by reduction of multi-dimensionality of $\langle \bar{k}^- | V G_0^{(+)} V | \bar{k}^+ \rangle$ integral.

1.) $|q^+\rangle \equiv V | \bar{k}^+ \rangle$ $\langle k' | T | k \rangle = \langle k' | q^+ \rangle + \langle q'^- | k \rangle - \langle q'^- | V^{-1} - G_0^{(+)} | q^+ \rangle$
 $\langle q'^- | \equiv \langle k'^- | V$ \rightarrow may be a problem

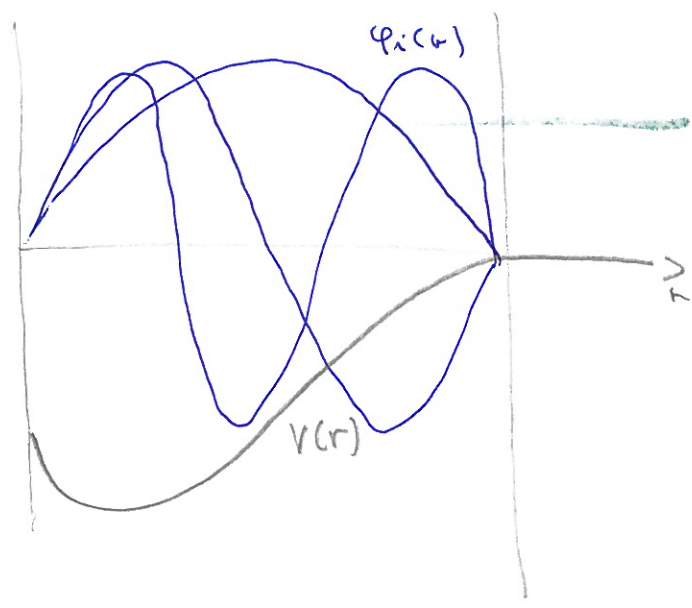
2.) Partial substitution (compromise)

$\langle q'^- | \equiv \langle k'^- | V$
 $\langle k' | T | k \rangle = \langle k' | V | \bar{k}^+ \rangle + \langle q'^- | k \rangle - \langle q'^- | V^{-1} - G_0^{(+)} V | \bar{k}^+ \rangle$

Schwinger variational method: solution in a basis

A comparison with the Kohn VP:

- L^2 basis is sufficient for finite range V , because $\langle \bar{k}^- |$ and $| \bar{k}^+ \rangle$ are always multiplied by V
- No boundary conditions in the basis because $G_0^{(+)}$ is taken care of that



Basis set
 $| \bar{k}^+ \rangle = \sum_i b_i | \varphi_i \rangle$
 $| \bar{k}^- \rangle = \sum_j c_j | \varphi_j \rangle$

$$[\langle k' | T | k \rangle] = \sum_i b_i \langle k' | V | \varphi_i \rangle + \sum_j c_j \langle \varphi_j | V | k \rangle - \sum_{ij} b_i c_j \langle \varphi_j | V - V G_0^{(+) } V | \varphi_i \rangle$$

$$1.) \frac{\partial [\langle k' | T | k \rangle]}{\partial b_i} = 0 \quad : \quad \langle k' | V | \varphi_i \rangle = \sum_j c_j \langle \varphi_j | V - V G_0^{(+) } V | \varphi_i \rangle$$

$$2.) \frac{\partial [\langle k' | T | k \rangle]}{\partial c_j} = 0 \quad : \quad \langle \varphi_j | V | k \rangle = \sum_i b_i \langle \varphi_j | V - V G_0^{(+) } V | \varphi_i \rangle$$

Define $(D^{-1})_{ji} = \langle \varphi_j | V - V G_0^{(+) } V | \varphi_i \rangle$

$$1.) \quad c_j = \sum_i \langle k' | V | \varphi_i \rangle D_{ij}$$

$$2.) \quad b_i = \sum_j D_{ij} \langle \varphi_j | V | k \rangle$$

After substitution into all the 3 terms become identical to each other

$$\boxed{[\langle k' | T | k \rangle] = \sum_{ij} \langle k' | V | \varphi_i \rangle D_{ij} \langle \varphi_j | V | k \rangle}$$

- Independent of the normalization $|k\rangle$ and $|k'\rangle$
- Most of L^2 bases work fine
- ~~Following~~ Following Schwinger-Lanczos method in which the basis $|\varphi_i\rangle$ is generated step-by-step for an optimal set with a small number of elements.

