

$$\varphi = \frac{1}{4\pi\epsilon_0} \int_0^{2\pi} \int \frac{\lambda R d\varphi}{\sqrt{r^2+z^2}} = \frac{1}{2\epsilon_0} \frac{\lambda R}{\sqrt{r^2+z^2}}$$

$$E_z = -\nabla_z \varphi$$

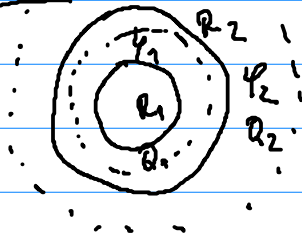
$$\begin{aligned} \varphi &= \int_z^\infty \vec{E} \cdot d\vec{r} = - \int_z^\infty E_z dz \\ &= -\frac{\lambda}{2\epsilon_0} \int_z^\infty \frac{R dz}{(z^2+r^2)^{3/2}} \end{aligned}$$

$$t = z^2 + r^2$$

$$dt = 2z dz$$

$$= -\frac{\lambda}{2\epsilon_0} \int_{z^2+r^2}^\infty \frac{R dt}{t^{3/2}} = +\frac{\lambda}{2\epsilon_0} \frac{R}{\sqrt{z^2+r^2}}$$

1.2.5.



$$(Q = CV)$$

$$C_{ij} = ?$$

$$Q_1 = C_{11} \varphi_1 + C_{12} \varphi_2$$

$$Q_2 = C_{21} \varphi_1 + C_{22} \varphi_2$$

$$\varphi = \dots \mathcal{A}(Q_1, Q_2)$$

$$\varphi_1 = B_{11} Q_1 + B_{12} Q_2$$

$$\varphi_2 = B_{21} Q_1 + B_{22} Q_2$$

$$C = B^{-1}$$

$$\rightarrow \varphi_1 = \frac{1}{4\pi\epsilon_0} \left(\frac{Q_1}{R_1} + \frac{Q_2}{R_2} \right)$$

$$E = \frac{1}{4\pi\epsilon_0} \frac{Q_1}{r^2}$$

$$\rightarrow \varphi(R_1) = \varphi_1 = \frac{1}{4\pi\epsilon_0} \frac{Q_1}{R_1} + C$$

$$\varphi(r) = \frac{1}{4\pi\epsilon_0} \frac{Q_1}{r} + C$$

$$r > r_2 \quad E = \frac{1}{4\pi\epsilon_0} \frac{Q_1 + Q_2}{r^2}$$

$$\varphi = \frac{1}{4\pi\epsilon_0} \frac{Q_1 + Q_2}{r} + C_2$$

$$\varphi(r_2) = \frac{1}{4\pi\epsilon_0} \frac{Q_1 + Q_2}{r_2} + C = \frac{1}{4\pi\epsilon_0} \frac{Q_1 + Q_2}{r_2}$$

$$C = \frac{1}{4\pi\epsilon_0} \frac{Q_2}{r_2}$$

$$\varphi_1 = \frac{1}{4\pi\epsilon_0} \left(\frac{Q_1}{r_1} + \frac{Q_2}{r_2} \right)$$

$$\varphi_2 = \frac{1}{4\pi\epsilon_0} \left(\frac{Q_1}{r_2} + \frac{Q_2}{r_2} \right)$$

$$B = \frac{1}{4\pi\epsilon_0} \begin{pmatrix} \frac{1}{r_1} & \frac{1}{r_2} \\ \frac{1}{r_2} & \frac{1}{r_2} \end{pmatrix}$$

$$C = B^{-1}$$

$$D = \frac{1}{r_1 r_2} - \frac{1}{r_2^2} = \frac{1}{r_2} \cdot \frac{r_2 - r_1}{r_1 r_2}$$

$$C = 4\pi\epsilon_0 \begin{pmatrix} \frac{1}{r_2} & -\frac{1}{r_2} \\ -\frac{1}{r_2} & \frac{1}{r_1} \end{pmatrix} \cdot \frac{1}{D} = 4\pi\epsilon_0 \frac{r_1 r_2}{r_2 - r_1} \cdot \begin{pmatrix} 1 & -1 \\ -1 & \frac{r_2}{r_1} \end{pmatrix}$$

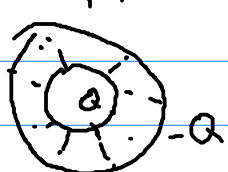
$$C_{11} = -C_{12} = -C_{21} = 4\pi\epsilon_0 \frac{r_1 r_2}{r_2 - r_1}$$

$$C_{22} = 4\pi\epsilon_0 \frac{r_2^2}{r_2 - r_1}$$

1.2.6

v 1.2.5

VRCTT $C \Rightarrow C_{ij}$

$$\begin{array}{l} Q_1 = Q \quad | \quad Q_2 = -Q \\ \varphi_1, \varphi_2 \rightarrow U = \varphi_2 - \varphi_1 \end{array}$$


$$\begin{array}{l} Q = C_{11} \varphi_1 + C_{12} \varphi_2 \\ -Q = C_{21} \varphi_1 + C_{22} \varphi_2 \end{array}$$

Dobro. D.Ú. $C = \Delta(C_{ij})$

$r_1 > r_2$ $\varphi = \dots \frac{Q-Q}{r} = 0$

$\varphi_2 = 0$

$U = -\varphi_1$

$Q = C_{11} \varphi_1 = -C_{11} U$

$-Q = C_{21} \varphi_1 = -C_{21} U$

$(-C_{11} = C_{21} = (-) 4\pi\epsilon_0 \frac{R_1 R_2}{R_2 - R_1})$

JINAK:



$U = \varphi_2 - \varphi_1 = \int_1^2 \vec{E} \cdot d\vec{r} =$

$E = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \cdot \frac{4\pi r^2}{R_1} = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$

$= \frac{Q}{4\pi\epsilon_0} \frac{R_2 - R_1}{R_1 R_2} \Rightarrow C = 4\pi\epsilon_0 \frac{R_1 R_2}{R_2 - R_1}$

KAPACITA VÁLCOVĚHO KOND.



$C = ?$

$U = \varphi_2 - \varphi_1 = \int \vec{E} \cdot d\vec{r}$

$E = \frac{1}{2\pi\epsilon_0} \cdot \frac{\lambda}{r}$

$\frac{\Sigma \cdot R_1^2}{2\epsilon_0 \cdot R}$

$\pi R_1^2 \rho = \lambda$

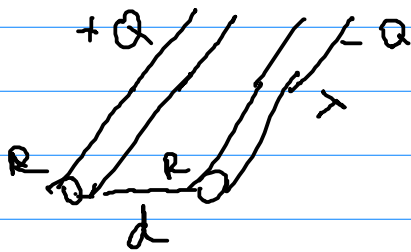
$\int_1^2 E \cdot dr = \int_{R_1}^{R_2} \frac{1}{2\pi\epsilon_0} \frac{\lambda}{r} dr = \frac{\lambda}{2\pi\epsilon_0} \int_{R_1}^{R_2} \frac{1}{r} dr$

$= \frac{\lambda}{2\pi\epsilon_0} \cdot \ln \frac{R_2}{R_1}$

$\frac{C}{l} = \frac{2\pi\epsilon_0}{\ln \frac{R_2}{R_1}}$

DŮ :

KAPACITA DVOJLINKY NA JEDN. DĚLEK



$$\frac{C}{l} = ?$$