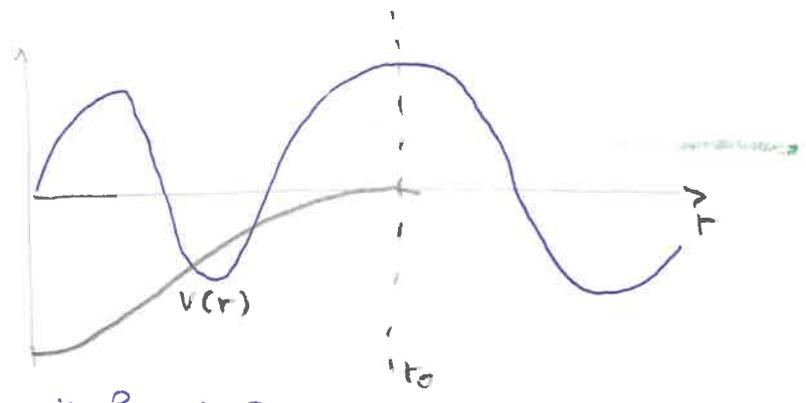


R-matrix method

- In the scattering we are looking for solutions of the Schrödinger equation with oscillatory asymptotic behaviour. The wf behavior is usually described by

- phase shift δ
- K-matrix $-\tan \delta$
- S-matrix $e^{2i\delta}$
- T-matrix $e^{i\delta} \sin \delta$
- Any other?



- Another way to define wf in outer region is B_e or R_e :

$$\left[-\frac{d^2}{dr^2} + \frac{l(l+1)}{r^2} + 2V(r) - k^2 \right] u_e(r) = 0$$

$$\begin{cases} u_e'(r_0) = B_e u_e(r_0) \\ u_e(r_0) = R_e u_e'(r_0) \end{cases} \quad \left. \begin{array}{l} \\ \end{array} \right\} R_e = B_e^{-1}$$

as a solution of

- Question: Is R_e sufficient for the scattering problem

- Two cases:

1.) $V(r) = 0$ for $r \geq r_0$: f_e, g_e are regular and irregular free solutions (riccati-bessel, neumann)

$$\begin{cases} u_e(r_0) = R_e u_e'(r_0) = A_e f_e(r_0) + B_e g_e(r_0) \\ \frac{1}{A_e} u_e(r_0) \rightarrow f_e(r_0) + K_e g_e(r_0) \end{cases} \quad \left. \begin{array}{l} \\ \end{array} \right\} K_e = -\frac{B_e}{A_e}$$

$$\begin{aligned} \frac{W(f_e, u_e)}{W(f_e, g_e)} &= B_e ; \quad \frac{W(g_e, u_e)}{W(g_e, f_e)} = A_e = -\frac{W(g_e, u_e)}{W(f_e, g_e)} \Rightarrow K_e = -\frac{B_e}{A_e} = + \frac{W(f_e, u_e)}{W(g_e, u_e)} \\ &= \frac{f_e u_e' - f_e' u_e}{g_e u_e' - g_e' u_e} = \frac{f_e - f_e' R_e}{g_e - g_e' R_e} = K_e \end{aligned}$$

2.) $V(r) \neq 0$ for $r \geq r_0$ In this case one can choose an arbitrary value of $u_e(r_0)$ (choice of the normalization) and R_e defines $u_e'(r_0) = R_e^{-1} u_e(r_0)$. Having value and the derivative allows to propagate the second-order dif. equation.

- History
- first: non-variational derivation, Wigner-Eisenbud 1947 nuclear physics, resonances. Sum-of-poles formula
- second: variational derivation, 1978 Kohn. Resolvent form
- third: eigenchannel formulation, Greene 1983, Szymtkowski 1997

Motivation

Is there a variational principle, similar to $E = \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle}$, for continuum states? What is the stationary quantity? It cannot be the energy as it is prescribed.

R-matrix (eigenchannel formulation)

(3dim, 1particle)

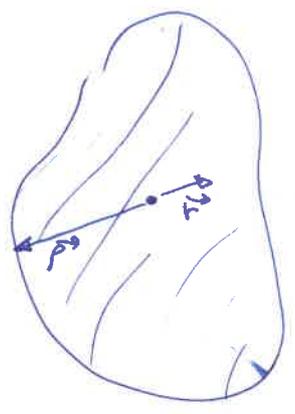
(R. Szymtkowski, J. Phys. A 30, 4913 (1997))

① Schrödinger equation

$(\hat{H} - E)\psi(E, \vec{r}) = 0$

in a finite volume V enclosed by S
 $V \subset \mathbb{R}^3$

$\hat{H} = -\frac{1}{2}\nabla^2 + V(\vec{r})$



volume vectors \rightarrow
 vectors \dots
 surface vectors \vec{p}

② Notation

$\langle f | g \rangle \equiv \int_V d^3r f^*(\vec{r}) g(\vec{r})$; $(f | g) = \int_S d^2p f^*(\vec{p}) g(\vec{p})$

Definition $\delta^{(2)}(\vec{p} - \vec{p}')$: $\int_S d^2p' \delta^{(2)}(\vec{p} - \vec{p}') f(\vec{p}') = f(\vec{p})$

Definition $D(E)$ space of functions, set of solutions $\psi(E, \vec{r})$ solving

$(\hat{H} - E)\psi(E, \vec{r}) = 0$

$\mathbb{D}_S(E)$ surface values of $D(E)$, i.e. $\psi(E, \vec{p})$

Lemma: for $\psi(E, \vec{r})$ and $\psi'(E, \vec{r}) \in D(E)$:

$\langle \hat{H} \psi' | \psi \rangle - \langle \psi' | H \psi \rangle = \frac{1}{2} (\psi' | \nabla_n \psi) - \frac{1}{2} (\nabla_n \psi' | \psi)$

the ... normal gradients

Proof: Divergence theorem (Gauss-Ostrogradsky)

$$\int_V \vec{\nabla} \cdot \vec{F} = \int_S \vec{F} \cdot \vec{n} ds, \text{ we choose } \vec{F} = u \vec{\nabla} v$$

$$\int_V (u \vec{\nabla}^2 v + \vec{\nabla} u \cdot \vec{\nabla} v) dv = \int_S u \underbrace{\vec{\nabla} v \cdot \vec{n}}_{\vec{\nabla}_n v} ds$$

One of the Gauss identities

$$\int_V (u \vec{\nabla}^2 v - v \vec{\nabla}^2 u) dv = \int_S (u \vec{\nabla}_n v - v \vec{\nabla}_n u) ds$$

- Because ψ and ψ' are solutions of $(\hat{H} - E)\psi(E, \vec{r}) = 0$ we may write:

$$\langle \psi' | \hat{H} \psi \rangle = \langle \hat{H} \psi' | \psi \rangle$$

- Formal interpretation is, that operator \hat{H} is Hermitian on class $D_S(E)$ with the scalar product (\cdot, \cdot) .

Definition on $D_S(E)$ we define a linear operators $\hat{B}(E)$ and $\hat{Q}(E)$

$$\left. \begin{aligned} \hat{H} \psi(E, \vec{r}) &= \hat{B}(E) \psi(E, \vec{r}) \\ \psi(E, \vec{r}) &= \hat{Q}(E) \hat{H} \psi(E, \vec{r}) \end{aligned} \right\} \hat{Q}(E) = \hat{B}^{-1}(E)$$

- Logderivative operator $\hat{B}(E)$ and R-matrix operator $\hat{Q}(E)$.
For a complete set of orthonormal functions $\phi_i(\vec{r})$ on S we may define matrix elements $(\phi_i | \hat{B}(E) | \phi_j)$, $(\phi_i | \hat{Q}(E) | \phi_j)$ of the logderivative matrix, R-matrix, respectively.

Eigenstates and eigenvalues of $\hat{B}(E)$ and $\hat{Q}(E)$

- Consider set of functions $\{\psi_i(E, \vec{r})\} \in D(E)$ that possess constant logderivative of the surface S :

$$\left. \begin{aligned} \hat{H} \psi_i(E, \vec{r}) - b_i(E) \psi_i(E, \vec{r}) &= 0 \\ \hat{B}(E) \psi_i(E, \vec{r}) &= b_i(E) \psi_i(E, \vec{r}) \end{aligned} \right\}$$

Surface values $\psi_i(E, \vec{r})$ are eigenvectors and $b_i(E)$ are eigenvalues of $\hat{B}(E)$

Because $\hat{B}(E)$ is Hermitian on $\mathcal{D}_S(E)$, $b_i(E) \in \mathbb{R}$ and $\psi_i(E, \vec{p})$ are orthonormal on S .

$$\left. \begin{aligned} (\psi_i | \psi_j) &= \delta_{ij} \\ \sum_i \psi_i(E, \vec{p}) \psi_i(E, \vec{p}') &= \delta^{(2)}(\vec{p} - \vec{p}') \end{aligned} \right\} \begin{array}{l} \text{orthonormal} \\ \text{complete} \end{array}$$

Variational principle for $b(E)$

- Generalized construction of the VP (we omit the index "i" in $\psi_i(E, \vec{p})$)
(Berjovoy 1983) Lagrange functions instead of Lagrange multipliers

Functional

$$F[\bar{b}, \bar{\lambda}, \bar{\Lambda}, \bar{\psi}] = \bar{b} + (\bar{\lambda} | \rho_m \bar{\psi} - \bar{b} \bar{\psi}) + \langle \bar{\Lambda} | \hat{H} - E | \bar{\psi} \rangle$$

- Instead of satisfaction of some scalar conditions we need a satisfaction of differential equations. Instead of λ (condition) we apply $\langle \bar{\lambda} | \bar{\psi} \rangle$. Projection of "0" on any trial $\bar{\lambda}$ is sought to be zero. Non-countable number of the Lagrange "multipliers". In a similar manner as one gets the equations for λ_i for the traditional "Lagrange-multipliers" system, we will get equations for functions $\bar{\lambda}(\vec{p})$ and $\bar{\Lambda}(\vec{r})$.

- For $\bar{\psi} \rightarrow \psi$ we get $F[b(E), \bar{\lambda}, \bar{\Lambda}, \psi] = b(E)$ regardless of $\bar{\lambda}(\vec{p})$ and $\bar{\Lambda}(\vec{r})$

- Our goal is to find such $\bar{\lambda}(\vec{p}), \bar{\Lambda}(\vec{r}), b(E)$ and $\psi(\vec{r})$ around which F becomes stationary with respect to small variations

$$\left. \begin{aligned} \delta b &= \bar{b} - b; & \delta \psi &= \bar{\psi} - \psi \\ \delta \lambda &= \bar{\lambda} - \lambda; & \delta \Lambda &= \bar{\Lambda} - \Lambda \end{aligned} \right\} \text{i.e. } \delta F[b, \lambda, \Lambda, \psi] = 0$$

Variation

$$\delta F[b, \lambda, \Lambda, \psi] = \delta b + (\delta \lambda | \rho_m \psi - b \psi) - \delta b (\lambda | \psi) + (\lambda | \rho_m \delta \psi - b \delta \psi) + \langle \delta \lambda | \hat{H} - E | \psi \rangle + \langle \lambda | \hat{H} - E | \delta \psi \rangle$$

$$\delta F[b, \lambda, \Lambda, \psi] = \delta b [1 - (\lambda | \psi)] + (\lambda | \rho_m \delta \psi - b \delta \psi) + \langle \lambda | \hat{H} - E | \delta \psi \rangle$$

$$\langle \lambda | \hat{H} - E | \delta \psi \rangle = \langle (\hat{H} - E) \lambda | \delta \psi \rangle + \frac{1}{2} (\rho_m \lambda | \psi) - \frac{1}{2} (\lambda | \rho_m \psi)$$

$$\delta F[b, \lambda, \Lambda, \psi] = \delta b [1 - (\lambda | \psi)] + \left(\frac{1}{2} \rho_m \lambda - b \lambda \right) | \delta \psi + \left(\lambda - \frac{1}{2} \Lambda | \rho_m \delta \psi \right) + \langle (\hat{H} - E) \lambda | \delta \psi \rangle$$

Free variations of $\delta b, \delta \lambda, \rho_m \delta \psi, \dots$ Requirement of the continuity of first derivatives is lifted

Lesson 2
Winter 2019

Resulting equations:

- (1.) $1 - (\lambda/\psi) = 0$
 - (2.) $(\hat{H} - E)\psi(\vec{r}) = 0$ in the volume V
 - (3.) $\lambda(\vec{p}) - \frac{\lambda(\vec{p})}{2} = 0$ on the surface S
 - (4.) $\frac{1}{2}\nabla_n \lambda(\vec{p}) - b(E)\lambda(\vec{p}) = 0$ on the surface S
- $$\left. \begin{array}{l} (3') \nabla_n \lambda(\vec{p}) - b(E)\lambda(\vec{p}) = 0 \\ (4') \frac{1}{2}\lambda(\vec{p}) = \lambda(\vec{p}) \end{array} \right\}$$

- Function $\lambda(\vec{r})$ satisfies in V and on S the same equations as (2) (3') as we require of $\psi(E, \vec{r})$. Therefore

$$\lambda(\vec{r}) = \gamma \psi(E, \vec{r})$$

Coefficient γ can be found through (4') and (1) as

$$\gamma = \frac{2}{\psi(\psi)}$$

$$\lambda(\vec{r}) = \frac{2}{\psi(\psi)} \psi(E, \vec{r})$$

$$\lambda(\vec{p}) = \frac{1}{\psi(\psi)} \psi(E, \vec{p})$$

Stationarity of $F[\lambda]$ requires in the stationary point

Therefore, we can reduce the variational space so that $\bar{\lambda}(\vec{r})$ and $\bar{\lambda}(\vec{p})$ will not be independent variations but they will

be bound to $\psi(E, \vec{r})$ exactly the same way as they are bound in the stationary point.

$$\bar{\lambda}(\vec{r}) = \frac{2}{\psi(\psi)} \bar{\psi}(E, \vec{r})$$

$$\bar{\lambda}(\vec{p}) = \frac{1}{\psi(\psi)} \bar{\psi}(\vec{p})$$

$$\text{Functional } F[\bar{\psi}] = \frac{(\bar{\psi} | \nabla_n \bar{\psi})}{(\bar{\psi} | \bar{\psi})} + 2 \frac{\langle \bar{\psi} | \hat{H} - E | \bar{\psi} \rangle}{(\bar{\psi} | \bar{\psi})} = \frac{(\nabla_n \bar{\psi} | \bar{\psi})}{(\bar{\psi} | \bar{\psi})} + 2 \frac{\langle (\hat{H} - E) \bar{\psi} | \bar{\psi} \rangle}{(\bar{\psi} | \bar{\psi})} = F^*[\bar{\psi}]$$

→ Functional $F[\lambda]$ is real for any trial function $\bar{\psi}$ (restriction to $\bar{\psi} \in D(E)$ is not needed)

→ Define $\bar{H} = \hat{H} + \frac{1}{2} \delta(S) \nabla_n$, where $\int_{R^3} d\vec{r}^3 f(\vec{r}) \delta(S) = \int_S ds f(\vec{p})$. Nonrestricted variational

principle for the eigenvalues $b(E)$ of the $\hat{B}(E)$ operator:

$$b(E) = \text{stat}_{\bar{\psi}} \left\{ 2 \frac{\langle \bar{\psi} | \bar{H} - E | \bar{\psi} \rangle}{(\bar{\psi} | \bar{\psi})} \right\}$$

$$\bar{H} = \hat{H} + \frac{1}{2} \delta(S) \nabla_n$$

Eigenchannel R-matrix; channels decomposition

$$b(E) = 2 \int_{\mathcal{V}} \frac{\langle \psi | \bar{H} - E | \psi \rangle}{\langle \psi | \psi \rangle} = 2 \frac{\langle \psi | \bar{H} - E | \psi \rangle}{\langle \psi | \delta(s) | \psi \rangle} \dots \text{we omit } \bar{\psi} \text{ bar}$$

$$\delta b = 0 = 2 \frac{\langle \delta \psi | \bar{H} - E | \psi \rangle + \langle \psi | \bar{H} - E | \delta \psi \rangle}{\langle \psi | \delta(s) | \psi \rangle} - \frac{2 \langle \psi | \bar{H} - E | \psi \rangle}{\langle \psi | \psi \rangle^2} \left[\langle \delta \psi | \delta(s) | \psi \rangle + \langle \psi | \delta(s) | \delta \psi \rangle \right]$$

$$0 = 2 \langle \delta \psi | \bar{H} - E | \psi \rangle - b \langle \delta \psi | \delta(s) | \psi \rangle + \text{complex conjugate}$$

$$(1) \quad \boxed{2 (\bar{H} - E) | \psi \rangle = b \delta(s) | \psi \rangle \equiv b | \psi \rangle}$$

(Greene 1983)

Volume basis $\{y_i\}$
 $\psi(\vec{r}) = \sum_j y_j(\vec{r}) c_j$

$$2 \sum_j \langle y_i | \bar{H} - E | y_j \rangle c_j = b \sum_j \langle y_i | \delta(s) | y_j \rangle c_j$$

Matrix eq:

$$\boxed{\underline{\Gamma}(E) \underline{c} = \underline{\Lambda} \underline{c} \underline{b}}$$

$$\Gamma_{ij} = 2 \langle y_i | \bar{H} - E | y_j \rangle = 2 (H_{ij} - S_{ij} E)$$

$$\Lambda_{ij} = \langle y_i | \delta(s) | y_j \rangle = (y_i | y_j)$$

$$S_{ij} = \langle y_i | y_j \rangle$$

Matrix $\underline{\Lambda}$ is singular, because on the surface S , the basis volume basis $\{y_i\}$ is overcomplete.

→ Define orthonormal basis on S : $\phi_\alpha(\vec{r})$, $(\phi_\alpha | \phi_\beta) = \delta_{\alpha\beta}$. This basis is called

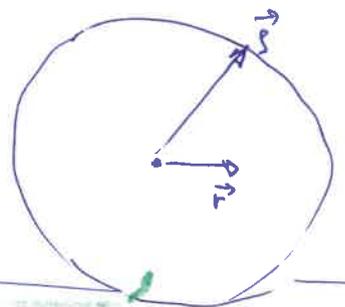
channels; Practical example:

$V =$ volume of a sphere r_0

$S =$ surface of the sphere r_0

$$\phi_\alpha = \frac{1}{r_0} Y_{lm}(\hat{r})$$

$$\alpha \equiv \{l, m\}$$



Eigen solutions of (1) will be projected onto ϕ_α on S :

$$\psi_i(E, \vec{r}) = \sum_\beta \phi_\beta(\vec{r}) F_{\beta i}$$

$$\left(\begin{matrix} \psi_i(E, \vec{r}) \\ \dots \\ \psi_m(E, \vec{r}) \end{matrix} \right) = \sum_\beta \phi_\beta(\vec{r}) \left(\begin{matrix} F_{\beta i} \\ \dots \\ F_{\beta m} \end{matrix} \right)$$

$$\psi_i(E, \vec{r}) = \hat{R} \psi_m(E, \vec{r})$$

$$\sum_\beta \phi_\beta(\vec{r}) F_{\beta i} = \sum_\beta \phi_\beta(\vec{r}) F_{\beta m} \hat{R} \phi_\beta(\vec{r})$$

$$F_{\alpha i} = \sum_\beta F_{\beta m} (\phi_\alpha | \hat{R} | \phi_\beta)$$

$$\boxed{\underline{F} = \underline{R} \underline{F}'} \iff \boxed{\underline{R} = \underline{F} \underline{F}'^{-1}}$$

$$(\psi_i | \psi_j) = \delta_{ij} = \sum_\alpha F_{\alpha i}^* F_{\alpha j} \Rightarrow \underline{1}_S = \underline{F}^+ \underline{F}$$

\underline{F} is unitary

$$\iff \psi_m(E, \vec{r}) = \hat{B}(E) \psi_i(E, \vec{r}) = b_i \psi_i(E, \vec{r})$$

$$\boxed{F'_{\alpha i} = F_{\alpha i} b_i} \quad \boxed{E' = E b}$$

Eigen channel R matrix (continued)

(7)

Projection coefficients of the basis $|y_i\rangle$ on the surface channels $\phi_\alpha(\vec{r})$

$$y_i(\vec{r}) = \sum_\alpha \phi_\alpha(\vec{r}) u_{i\alpha}^* ; \Lambda_{ij} = (y_i | y_j) = \sum_{\alpha\beta} u_{i\alpha} u_{j\beta}^* \underbrace{(\phi_\alpha | \phi_\beta)}_{\delta_{\alpha\beta}} = \sum_\alpha u_{i\alpha} u_{j\alpha}^*$$

$$\boxed{u_{i\alpha}^* = (\phi_\alpha | y_i) \Rightarrow u_{i\alpha} = (y_i | \phi_\alpha)}$$

$|y_i\rangle$ are eigenstates of the Hermitian operator $\hat{B} \Rightarrow (y_i | y_j) = \delta_{ij} \Leftrightarrow \underline{C}^+ \Lambda \underline{C} = \mathbb{1}$

$$\underline{C} \underline{C}^+ \Lambda \underline{C} \underline{C}^+ = \underline{C} \underline{C}^+ \Rightarrow \underline{C} (\Lambda \underline{C})^{-1} = \underline{C}^+ \quad \text{(A)}$$

(B)

One more identity: $F_{\alpha i} = (\phi_\alpha | \psi_i) = \sum_j (\phi_\alpha | y_j) C_{ji} = \sum_j C_{ji} u_{j\alpha}^*$; Matrix form: $\underline{F} = \underline{U}^+ \underline{C}$

Back to R matrix

$$\underline{R} = \underline{F} \underline{F}^{-1}$$

$$F_{\alpha i} = F_{\alpha i} b_i$$

\underline{F} is unitary

$$R_{\alpha\beta} = \sum_i F_{\alpha i} (F^{-1})_{i\beta} ; \delta_{\alpha\beta} = \sum_i F_{\alpha i} F_{\beta i} = \sum_i \underbrace{F_{\alpha i}^* b_i}_{F_{\alpha i}^* \Rightarrow (F^{-1})_{i\alpha}} \underbrace{b_i^{-1} F_{\beta i}}_{(F^{-1})_{i\beta} = F_{\beta i}^* b_i^{-1}}$$

$$R_{\alpha\beta} = \sum_i F_{\alpha i} F_{\beta i}^* b_i^{-1} \Leftrightarrow \underline{R} = \underline{F} \underline{b}^{-1} \underline{F}^+$$

\underline{b}^{-1} is diagonal
Eigen channel form of R matrix

Transforming the eigenchannel form through (B): $\underline{R} = \underline{F} \underline{b}^{-1} \underline{F}^+ = \underline{U}^+ \underline{C} \underline{b}^{-1} \underline{C}^+ \underline{U}$

Identity from the eigenvalue equation:

$$\underline{R} = \underline{U}^+ \underline{C} \underline{b}^{-1} \underline{C}^+ \underline{U} = \underline{U}^+ \underline{\Gamma}^{-1} \underline{U}$$

$$\underline{\Gamma} \underline{C} = \underline{\Lambda} \underline{C} \underline{b}$$

$$\underline{C} = \underline{\Gamma}^{-1} \underline{\Lambda} \underline{C} \underline{b}$$

$$\underline{C} \underline{b}^{-1} = \underline{\Gamma}^{-1} \underline{\Lambda} \underline{C}$$

$$\underline{C} \underline{b}^{-1} \underline{C}^+ = \underline{\Gamma}^{-1} \underline{\Lambda} \underline{C} \underline{C}^+ = \underline{\Gamma}^{-1} \quad \text{(A) } \mathbb{1}$$

$$R_{\alpha\beta} = \sum_{ij} (\phi_\alpha | y_i) [2(\bar{H} - E_S)]^{-1}_{ij} (y_j | \phi_\beta)$$

Kohn's derivation 1948 generalized to 3D
(Resolvent form)

Spectral decomposition, poles expansion, Wigner-Eisenbud form

Define: $\Lambda_{ij} = \bar{H}_{ij} - S_{ij} E$

Our goal is to compute A^{-1} through the spectral decomposition of \bar{H}

Eigenvalues and eigenvectors of $\bar{H} = H + \frac{1}{2} \delta(\epsilon) V_m$ (\bar{H} is Hermitian inside the volume)

in generally non-orthogonal basis $|y_i\rangle$

$$\bar{H} |N_p\rangle = \sum_p |N_p\rangle$$

$$|N_p\rangle = \sum_j V_{jp} |y_j\rangle$$

$$\sum_j \langle y_i | \bar{H} |y_j\rangle V_{jp} = \sum_\alpha \sum_j V_{jp} \underbrace{\langle y_i | y_j \rangle}_{S_{ij}} \leftarrow \text{overlap matrix}$$

Matrix form:
$$\underline{\bar{H}} \underline{V} = \underline{S} \underline{V} \underline{\Sigma}$$

$\underline{\Sigma}$ is diagonal
Generalized eigenvalue problem
(eigenvalue problem in an non-orthogonal basis)

Because $\langle N_p | N_q \rangle = \delta_{pq} = \sum_{ij} V_{ip}^* V_{jq} S_{ij} \iff \underline{V}^T \underline{S} \underline{V} = \underline{I}$ (A)

$$\underline{\bar{H}} = \underline{S} \underline{V} \underline{\Sigma} \underline{V}^T \underline{S}$$

to be compared with the case of the orthonormal basis, where $\underline{\bar{H}} = \underline{V} \underline{\Sigma} \underline{V}^T$

This spectral decomposition of \hat{H} allows the following:

$$\begin{aligned} \underline{A}^{-1} &= (\underline{\bar{H}} - E \underline{S})^{-1} = [(\underline{S} \underline{V} \underline{\Sigma} \underline{V}^T - E \underline{S}) \underline{S}]^{-1} = \underline{S}^{-1} (\underline{S} \underline{V} \underline{\Sigma} \underline{V}^T - E \underline{S} \underline{V} \underline{V}^T)^{-1} \\ &= \underline{S}^{-1} [\underline{S} \underline{V} (\underline{\Sigma} - E) \underline{V}^T]^{-1} = \underline{S}^{-1} \underline{V}^{-1} (\underline{\Sigma} - E)^{-1} (\underline{S} \underline{V})^{-1} = \underline{V} (\underline{\Sigma} - E)^{-1} \underline{V}^T \end{aligned}$$

$$\underline{A}^{-1} = \underline{V} (\underline{\Sigma} - E)^{-1} \underline{V}^T$$

→ put inside the resolvent form of Kohn

$$R_{\alpha\beta} = \frac{1}{2} \sum_{ij} \sum_p \underbrace{\langle \phi_\alpha | \delta(s) | y_i \rangle}_{\text{with } \underline{\Sigma}_i \text{ it gives } |N_p\rangle} V_{ip} \frac{1}{\Sigma_p - E} \underbrace{V_{jp}^* \langle y_j | \delta(s) | \phi_\beta \rangle}_{\text{with } \underline{\Sigma}_j \text{ we have } \langle N_p |}$$

$$R_{\alpha\beta} = \frac{1}{2} \sum_p \frac{(\phi_\alpha | N_p) (N_p | \phi_\beta)}{\Sigma_p - E}$$

Wigner-Eisenbud form 1942
Expansion over the poles of \bar{H}

$(\phi_\alpha | N_p)$... surface amplitudes, projection of the p -th eigenfunction $|N_p\rangle$ onto the α -th surface channel