

①

B. Polynomial interpolation

Lagrange interpolation

$\mathcal{B} = C[a, b]$, $A = P_m$ polynomials of degree at most m

Problem

Given $f \in C[a, b]$ and $m+1$ distinct points x_0, x_1, \dots, x_n of $[a, b]$.

Look for $p \in P_m$ s.t.

$$(*) \quad p(x_i) = f(x_i), \quad i=0, \dots, m.$$

\nearrow
 the Lagrange
 interpolation pol.
 $x_i \dots$ interpol. points

Recall: a construction of p satisfying $(*)$

$$l_j(x) \equiv \prod_{\substack{i=0 \\ i \neq j}}^m \frac{x - x_i}{x_j - x_i} \quad \dots \text{the } j\text{th Lagrange pol.}$$

$l_j \in P_m$, $l_j(x_i) = \delta_{ij} \Rightarrow l_0, \dots, l_m$ a basis of P_m

Then $p(x) = \sum_{j=0}^m f_j l_j(x)$, f_j determined such that $(*)$ holds.
 $\Rightarrow f_j = f(x_j)$

Lagrange 1795, Euler 1783

$$(**) \quad L_m(x) \equiv \sum_{j=0}^m f(x_j) l_j(x) \in P_m \text{ and satisfies } (*).$$

\nwarrow the Lagrange interpolation formula

Theorem: There is exactly one polynomial $p \in P_m$ that satisfies $(*)$.

Proof. We have shown the existence, uniqueness by contradiction. \square

• Interpolation process is an operator $X : f \in C[a, b] \mapsto p_m(x) \in P_m$
 \downarrow
 depends on the choice of x_i

From $(**)$ it is obvious that X is a linear projection.

X is a projection $\Rightarrow \forall q \in P_m : L_m(x) = \sum_{j=0}^m q(x_j) l_j(x)$, and $q(x)$ agree in $m+1$ points
 In particular, for $q(x) \equiv 1$ we get
 \Rightarrow must be equal everywhere

$$(+)\quad 1 = \sum_{j=0}^m l'_j(x)$$

• Computationally \rightarrow to evaluate $L_m(x)$ using $(**)$ we need $O(m^2)$ operations.

- One can use (+) to improve the operation count.

- Define the node polynomial

$$w(x) = \prod_{i=0}^m (x - x_i). \quad (W_{m+1}(x))$$

Then

$$l_j(x) = \prod_{\substack{i=0 \\ i \neq j}}^n \frac{x - x_i}{x_j - x_i} = w(x) \frac{\lambda_j}{x - x_j}, \quad \lambda_j = \frac{1}{\prod_{\substack{i=0 \\ i \neq j}}^m (x_j - x_i)}$$

Since $l_j(x) = \frac{w(x)}{w'(x_j)(x - x_j)}$, we have $\lambda_j = \frac{1}{w'(x_j)}$.

$$\text{cond}(x_m, j) = \frac{\sum_{j=0}^m |l_j(x)| f_j}{|L_m(x)|}$$

$$(++) \quad L_m(x) = w(x) \sum_{j=0}^m \frac{\lambda_j}{x - x_j} \cdot f_j \quad (f_j = f(x_j))$$

modified Lagrange formula, Jacobi 1825

- If weights λ_j are known \rightarrow only $O(m)$ operations to evaluate $L_m(x)$

- Comp. weights requires $O(m^2)$ op. \rightarrow needs to be done just once

- For special grids $\rightarrow \lambda_j$ are known.

$$\text{forward stable} \quad \frac{|L_m(x) - L_m(\bar{x})|}{|L_m(x)|} \leq O(m) \text{M} \frac{1}{\text{cond}(x_m, j)}$$

It holds that

$$1 = \sum_{j=0}^m l_j(x) = w(x) \sum_{j=0}^m \frac{\lambda_j}{x - x_j} \Rightarrow w(x) = \sum_{j=0}^m \frac{x_j}{x - x_j}$$

Use (++)

$$L_m(x) = \frac{\sum_{j=0}^m \frac{\lambda_j}{x - x_j} \cdot f_j}{\sum_{j=0}^m \frac{\lambda_j}{x - x_j}}$$

barycentric interpolation

\rightarrow used by Chebfun for interpolation
in Chebyshev points $|L_m(x) - L_m(\bar{x})| \leq O(m) |\text{cond}(x_m, j)| + L_m$
 \rightarrow numerically stable (forward) for reasonable sets of int. points

- for a general distribution of points
better to use (++)

- Note
• Newton interpolation formula - another form \rightarrow we can add interpolation points, using divided differences. It can be shown \checkmark divided diff. \checkmark of order m+2

$$L_{m+1}(x) = L_m(x) + \prod_{j=0}^m (x - x_j) f[x_0, x_1, \dots, x_m, x_{m+1}],$$

\rightarrow square brackets

where $f[x_j] \equiv f(x_j)$,

$$f[x_j, x_{j+1}, \dots, x_{j+k+1}] = \frac{f[x_{j+1}, \dots, x_{j+k+1}] - f[x_j, \dots, x_{j+k}]}{x_{j+k+1} - x_j}$$

Then, by induction,

$$L_m(x) = f(x_0) + (x - x_0) f[x_0, x_1] + (x - x_0)(x - x_1) f[x_0, x_1, x_2] + \dots + \prod_{j=0}^{m-1} (x - x_j) f[x_0, \dots, x_m].$$

the Newton interpolation formula

[Powell, Theorem 5.2]

(3)

The error in polynomial interpolation

We are interested in the error function,

$$e(x) = f(x) - L_m(x), \quad a \leq x \leq b.$$

Let x_0, \dots, x_m and $x \neq x_i$, $i=0, \dots, m$ are given. Define $x_{m+1} = x$ and use the relation

$$f(x) = L_{m+1}(x) = L_m(x) + \underbrace{\prod_{j=0}^m (x-x_j)}_{w(x)} f[x_0, x_1, \dots, x_m, x]$$

Hence

$$e(x) = f(x) - L_m(x) = w(x) f[x_0, x_1, \dots, x].$$

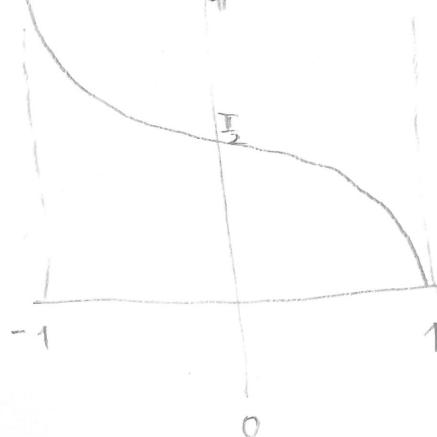
Let $f \in C^{(m+1)}[a, b]$. Then $\forall x \in [a, b] \exists \xi_x \in (a, b)$:

$$e(x) = \frac{f^{(\xi_x)}}{(m+1)!} w(x).$$

Proof. Use Rolle's theorem several times. \square

- By the choice of x_i we influence the size of $|e(x)|$.
 - What is a reasonable distribution of interpolation points that gives "small" $\|e(x)\|_\infty$?
 - It is hard to predict the influence of x_i so $f^{(\xi_x)} \rightarrow$ suppose that it is bounded.
 - Choose x_i such that $\|w(x)\|_\infty = \left\| \prod_{j=0}^m (x-x_j) \right\|_\infty$ is minimal.
- ↓
Chebyshev points.

The Chebyshev polynomials



$$[-1, 1] \xrightarrow{\cos^{-1}} [0, \pi]$$

$$x \leftrightarrow \theta$$

$$x = \cos \theta$$

\hookrightarrow nonlinear, but
one-to-one (bijection)

Consider, on $[0, \pi]$, the functions

$$1, \cos \theta, \cos 2\theta, \dots, \cos k\theta,$$

and transform them onto $[-1, 1]$ using the \cos^{-1} mapping - On $[-1, 1]$, we get

$$\begin{array}{ccccccc} 1, \cos(\cos^{-1}(x)), \cos(2\cos^{-1}(x)), \dots, & \cos(k\cos^{-1}(x)) \\ \downarrow & \downarrow & & & \downarrow \\ T_0(x) = 1 & T_1(x) = x & T_2(x) & & T_k(x) \end{array}$$

It holds that

$$\underbrace{\cos((k+1)\theta)}_{T_{k+1}(x)} + \underbrace{\cos((k-1)\theta)}_{T_{k-1}(x)} = 2 \cos(\theta) \cos(k\theta) = 2 \times T_k(x)$$

Therefore

$$\begin{aligned} T_0(x) &= 1 \\ T_1(x) &= x \end{aligned}$$

$$\text{and } T_{k+1}(x) = 2xT_k(x) - T_{k-1}(x), \quad k = 1, \dots$$

$\Rightarrow T_k(x)$ are polynomials called Chebyshev polynomials.

Properties

Roots

$$0 = T_k(x) = \cos(k\cos^{-1}(x))$$

should be odd multiples of $\frac{\pi}{2}$

$$x_j = \cos\left(\frac{(2j-1)\pi}{2k}\right), \quad j = 1, \dots, k$$

k real distinct roots in $(-1, 1)$

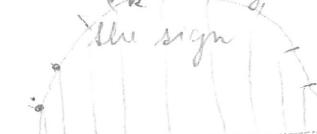
Extrema occurs for

$$x_j = \cos\left(\frac{j\pi}{k}\right), \quad j = 0, \dots, k$$

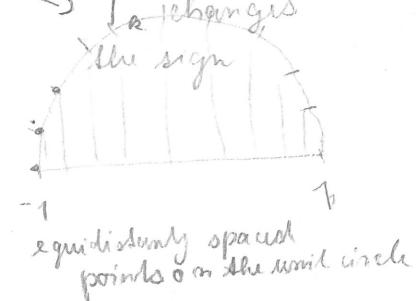


T_k changes

$$\text{Obvious } \max_{x \in [-1, 1]} T_k(x) = 1, \quad \min_{x \in [-1, 1]} T_k(x) = -1$$



$$\begin{aligned} 1 &= T_k(x) \Leftrightarrow k\cos^{-1}(x) = 0, 2\pi, 4\pi, \dots \\ -1 &= T_k(x) \Leftrightarrow k\cos^{-1}(x) = \pi, 3\pi, 5\pi, \dots \end{aligned}$$



Orthogonality of polynomials with respect to the weight

$$w(x) = \sqrt{1-x^2}$$

$$\int_{-1}^1 T_m(x) T_n(x) \frac{1}{\sqrt{1-x^2}} dx = \int_{-\pi}^{\pi} \cos(m\theta) \cos(n\theta) d\theta = \begin{cases} 0 & m \neq n \\ \pi & m = n = 0 \\ \frac{\pi}{2} & m = n \neq 0 \end{cases}$$

substitution

$$x = \cos \theta$$

$$\theta = \cos^{-1} x$$

$$d\theta = -\frac{dx}{\sqrt{1-x^2}}$$

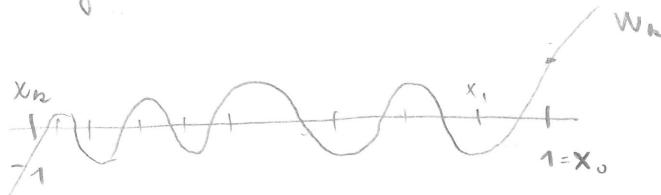
Theorem The monic polynomial $W_n(x) = \frac{1}{2^{n-1}} T_n(x)$

mimimises the maximum on $[-1, 1]$ over all monic polynomial of degree k .

Proof. By contradiction. Let there exist a monic pol. $V_k(x) \neq 1$.

$$(*) \quad \max_{x \in [-1, 1]} |V_k(x)| < \max_{x \in [-1, 1]} |W_k(x)|, \quad j=0, \dots, k.$$

The maximum of $|W_k(x)|$ on $[-1, 1]$ occurs at the points $x_j = \cos\left(\frac{j\pi}{k}\right)$.



- At x_0 , using $(*)$, $W_k(x_0) > V_k(x_0)$ etc.
- At x_1 , $W_k(x_1) < V_k(x_1)$

$\Rightarrow W_k(x) - V_k(x)$ changes the sign k times $\Rightarrow k$ roots
but $\deg(W_k - V_k) < k \rightarrow$ contradiction. \square

Back to interpolation

- If we choose interpolation points as

$$(**) \quad x_j = \cos\left(\frac{(2(m-j)+1)\pi}{2(m+1)}\right), \quad j=0, \dots, m, \quad \text{L} \rightarrow \text{ordered roots of } T_{m+1}$$

W_k solves $\min_{\text{polys}} \max_{x \in [-1, 1]} |p(x)|$
 $\|p\|_\infty$

Then

$$w(x) = \frac{1}{2^m} T_{m+1}(x)$$

has the smallest possible $\|w\|_\infty$ (the smallest deviation from 0).

Points $(**)$ are called Chebyshev points of the first kind.

- In practical computations we use Chebyshev extreme points

$$(***) \quad x_j = \cos\left(\frac{(m-j)\pi}{m}\right), \quad j=0, \dots, m$$

\rightarrow analogous approximation properties, contain boundary points

Chebyshev points of second kind \rightarrow we just say Chebyshev points

- For $[a, b]$ we use the linear transformation onto $[-1, 1]$

$$y = \frac{x(b-a)+a+b}{2}$$

$$[-1, 1] \leftrightarrow [a, b]$$

$$x \quad y$$

Then,

$$y_j = \lambda + \mu \cos\left(\frac{(m-j)\pi}{m}\right),$$

$$\lambda = \frac{1}{2}(a+b)$$

$$\mu = \frac{1}{2}(b-a).$$

Chebyshev interpolants and the barycentric interpolation formula (6)

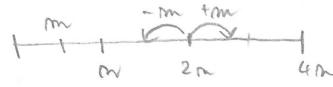
Cheb. interpolants ... Lagrange interpolant in Cheb. points.

Aliasing of Cheb. polynomials.

Lemma. Let $x_j = \cos\left(\frac{j\pi}{m}\right)$, $j=0, \dots, m$. Then, for $0 \leq m \leq n$, it holds that

$$T_m(x_j) = T_{2m-m}(x_j) = T_{2m+m}(x_j).$$

4m, 6m ...



Proof.

$$T_m(x) = \cos(m \cos^{-1}(x)).$$

- $T_m(x_j) = \cos(m \frac{j\pi}{m})$
- $T_{2m-m}(x_j) = \cos((2m-m)\frac{j\pi}{m}) = \cos(2j\pi - m \frac{j\pi}{m}) = \cos(m \frac{j\pi}{m})$
= $\cos(m \frac{j\pi}{m})$. \square
- $T_{2m+m}(x_j) = \dots$

In particular, for $m = m-1$ we obtain

$$T_{m-1}(x_j) = T_{m+1}(x_j), \quad j=0, \dots, m$$



$$\underbrace{\frac{1}{2m} (T_{m+1}(x) - T_{m-1}(x))}_{\text{is monic}} = w_{m+1}(x)$$

\Rightarrow

$$= 0 \text{ at } x_j, \quad x_j = 0, \dots, m$$

Recall

$$l_j(x) = w_{m+1}(x) \frac{x_j - x}{x_j}, \quad \lambda_j = \frac{1}{w'_{m+1}(x_j)}.$$

Therefore

$$\lambda_j = \frac{2^m}{T'_{m+1}(x_j) - T'_{m-1}(x_j)} \quad \text{if } x_j \text{ are Cheb. points.}$$

Lemma Let $x_j = \cos\left(\frac{j\pi}{m}\right)$, $j=0, \dots, m$. Then

$$\begin{cases} \lambda_j = \frac{2^{m-1}}{m} (-1)^j & \text{for } j=1, \dots, m-1, \text{ and} \\ \lambda_j = \frac{1}{2} \left[\frac{2^{m-1}}{m} (-1)^j \right] & \text{for } j=0 \text{ and } j=m. \end{cases}$$

Proof. If $x \in (0, 1)$, then

$$\bullet \quad \frac{d}{dx} T_k(x) = \frac{d}{dx} (\cos(k \cos^{-1}(x))) = k \frac{\sin(k \cos^{-1}(x))}{\sin(\cos^{-1}(x))}.$$

$$\begin{aligned} \sin(\cos^{-1}(x))' &= -\frac{1}{\sqrt{1-x^2}} \quad \text{and} \quad x \in (0, 1) \\ \sqrt{1-x^2} &= \sqrt{\sin^2 \theta} = |\sin \theta| = |\sin(\cos^{-1}(x))| = \sin(\cos^{-1}(x)) \end{aligned}$$

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Then

$$\begin{aligned} T'_{m+1}(x_j) - T'_{m-1}(x_j) &= (m+1) \frac{\sin((m+1)\frac{j\pi}{m})}{\sin(j\frac{\pi}{m})} - (m-1) \frac{\sin((m-1)\frac{j\pi}{m})}{\sin(j\frac{\pi}{m})} \\ &= \frac{(m+1) \sin(j\pi + \frac{\pi}{m}) - (m-1) \sin(j\pi - \frac{\pi}{m})}{\sin(j\frac{\pi}{m})} \\ &\stackrel{j \text{ even}}{=} \frac{(m+1) \sin(\frac{j\pi}{m}) - (m-1) \sin(-\frac{j\pi}{m})}{\sin(j\frac{\pi}{m})} = 2m \\ &\stackrel{j \text{ odd}}{=} \frac{(m+1) \sin(-\frac{j\pi}{m}) - (m-1) \sin(\frac{j\pi}{m})}{\sin(j\frac{\pi}{m})} = -2m \end{aligned}$$

 T'_n is continuous, differentiablefor $x = \pm 1$ take the limit

$$T'_k(1) = \lim_{\substack{x \rightarrow 1^+ \\ x_0}} k \frac{\sin(k \cos^{-1}(x))}{\sin(\cos^{-1}(x))} = \lim_{\theta \rightarrow 0^+} k \frac{\sin(k\theta)}{\sin\theta} = k^2$$

$$T'_k(-1) = \lim_{\substack{\theta \rightarrow \pi^- \\ x_m}} k \frac{\sin\theta k}{\sin\theta} = \begin{cases} k^2 & \text{if } k \text{ is even} \\ -k^2 & \text{if } k \text{ is odd} \end{cases}$$

and

$$T'_{m+1}(x_0) - T'_{m-1}(x_0) = (m+1)^2 - (m-1)^2 = 4m = 2(-1)^j 2m \quad \text{for } j=0,$$

$$T'_{m+1}(x_m) - T'_{m-1}(x_m) = \left\langle \begin{array}{c} 4m \text{ (even m)} \\ -4m \text{ (odd m)} \end{array} \right\rangle = 2(-1)^j 2m \quad \text{for } j=m. \quad \square$$

Theorem The polynomial interpolant through data $\{f_j\}$ at the Chebyshev points $x_j = \cos\left(\frac{j\pi}{m}\right)$, $j=0, \dots, m$ is

$$L_m(x) = \frac{\sum_{j=0}^{m-1} (-1)^j f(x_j)}{\sum_{j=0}^{m-1} \frac{(-1)^j}{x-x_j}},$$

The primes on the summation signs signify that the terms $j=0$ and $j=m$ are multiplied by $\frac{1}{2}$.

Proof. Barycentric formula

$$L_m(x) = \frac{\sum_{j=0}^m \frac{\lambda_j}{x-x_j} f_j}{\sum_{j=0}^m \frac{\lambda_j}{x-x_j}} \quad \text{and} \quad \begin{aligned} \lambda_j &= \frac{2^{m-1}}{m} (-1)^j, \quad j=1, \dots, m-1 \\ \lambda_0 &= \frac{1}{2} \frac{2^{m-1}}{m} (-1)^0, \quad j=0, j=m. \end{aligned} \quad \square$$

- extraordinarily effective $O(n)$ operations
- good num. properties

The norm of the Lagrange interpolation operator

For distinct $x_0, \dots, x_m \in [a, b]$ define the Lebesgue function

$$L(x) = \sum_{j=0}^m |l_j(x)|$$

$$\|L\|_\infty \stackrel{\text{def}}{=} \max_{x \in [a, b]} L(x) \quad \text{the Lebesgue constant}$$

Theorem Let x_0, \dots, x_m be distinct points from $[a, b]$. Consider the Lagrange interpolation operator $X : C[a, b] \rightarrow P_m$,

$$X : f \mapsto L_m, \quad L_m(x_i) = f(x_i), \quad i = 0, \dots, m. \quad \text{Then}$$

$$\|X\|_\infty = \|L\|_\infty. \quad [\text{Cheney, Light 2000, p. 13}]$$

Proof. It holds that

$$\begin{aligned} \stackrel{(\leq)}{\leq} \|X(f)\|_\infty &= \max_{x \in [a, b]} |(Xf)(x)| = \max_{x \in [a, b]} \left| \sum_{i=0}^m f(x_i) l_i(x) \right| \\ &\leq \max_{x \in [a, b]} \sum_{i=0}^m |f(x_i)| |l_i(x)| \leq \|L\|_\infty \|f\|_\infty \\ &\quad \Downarrow \\ &\|X\|_\infty \leq \|L\|_\infty. \end{aligned}$$

$$\stackrel{(\geq)}{\geq} \exists \xi \in [a, b] : L(\xi) = \|L\|_\infty.$$

- Choose $f \in C[a, b] : \|f\|_\infty = 1$ and $f(x_i) = \operatorname{sgn} l_i(\xi)$.

- Then

$$\|X\|_\infty \geq \|Xf\|_\infty \geq (Xf)(\xi) = \sum_{i=0}^m f(x_i) l_i(\xi) = \sum_{i=0}^m |l_i(\xi)| = \|L\|_\infty. \quad \square$$

Second motivation for the choice of x_i :

$$\|X(f) - f\|_\infty \leq (1 + \|X\|_\infty) \min_{p \in P_m} \|f - p\|_\infty$$

choose x_i such that $\|X\|_\infty$ is small.

$$L_m \geq \dots$$

Theorem (Faber 1914). Suppose that we are given $m+1$ distinct interpolation points from $[a, b]$. Then $\exists f \in C[a, b] : \|f - L_m f\|_\infty \rightarrow 0$ as $m \rightarrow \infty$.

(no sets of interpolation points can lead to convergence $\forall f \in C[a, b]$). \uparrow

Hence

$$\limsup_{m \rightarrow \infty} L_m = \infty.$$

\uparrow
a consequence
of a more general
theorem we
discussed

present first $L_m \geq \dots$, then Faber's theorem follows.

(9)

Theorem: Denote L_m the Lebesgue constant for a given set of $m+1$ distinct interpolation points in $[-1, 1]$. Then

$$L_m \geq \frac{2}{\pi} \log(m+1) + 0.52125\dots$$

[Bernstein 1912
Jackson 1913
Faber 1914]

For Chebyshev points of the first and second kind it holds that

$$L_m \leq \frac{2}{\pi} \log(m+1) + 1.$$

For equispaces points

$$L_m > \frac{2^{m-2}}{m^2}.$$

→ to know more about convergence, study

$$\begin{aligned} \frac{2}{\pi}(\gamma + \log(\frac{4}{\pi})) &\rightarrow \text{natural log} \\ \hookrightarrow \text{Euler's constant } 0.577\dots \\ \lim_{n \rightarrow \infty} (-\log n + \sum_{k=1}^n \frac{1}{k}) &= -\int_0^\infty e^{-x} \log(x) dx \end{aligned}$$

Convergence of Chebyshev interpolants

Chebyshev polynomials form an orthogonal system of functions in $C[-1, 1]$,

$$\langle p_i, q_j \rangle = \int_{-1}^1 p_i \cdot q_j \cdot \frac{1}{\sqrt{1-x^2}} dx \quad \text{the best approx of } f \text{ in the induced norm.}$$

One can project any $f \in C[-1, 1]$ to this system

$$f \longmapsto \sum_{i=0}^{\infty} \frac{\langle f, T_i \rangle}{\langle T_i, T_i \rangle} T_i = \frac{2}{\pi} \sum_{i=0}^{\infty} \langle f, T_i \rangle T_i + \frac{1}{\pi} \langle f, T_0 \rangle.$$

[REF. Thm 3.1]

Theorem: If f is Lipschitz continuous on $[-1, 1]$, it has a unique representation as a Chebyshev series,

$$f(x) = \sum_{i=0}^{\infty} a_i T_i(x), \quad a_i = \frac{2}{\pi} \langle f, T_i \rangle, \quad a_0 = \frac{1}{\pi} \langle f, T_0 \rangle.$$

which is absolutely and uniformly convergent.

Proof: Based on Dirichlet-Lipschitz criterion - later.

continuous
M-12

[REF. P-25]

$$f_m(x) = \sum_{i=0}^m a_i T_i(x), \quad a_i \text{ defined as above}$$

* 12 L_m

truncation

Chebyshev projection

for periodic functions



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Page about connections

done

is as good as f_m in the sense of bounds?

(case like)

Theorem: If f is Lipschitz continuous on $[-1, 1]$, then

$$\|f - p_m\|_{\infty} \leq 2 \|f - f_m\|_{\infty},$$

where p_m is the Chebyshev interpolant.

Consequence: p_m is as good as f_m . (for f Lipschitz)

Cheb series converges

constant 2

=>

p_m converges absolutely and uniformly

$$\|f - p_m\|_{\infty} \rightarrow 0$$

27.10.2016

Theorem (Speed of convergence for differentiable function)

Let $f \in C[a, b]$. Let $f^{(n)}$, $n=1, \dots, N-1$, $\forall n \in \mathbb{N} (N \geq 1)$ be absolutely continuous and suppose that $f^{(N)}$ is of bounded variation V . Then $\|f - p_m\|_\infty$ its Chebyshev interpolants satisfy

$$\|f - p_m\|_\infty \leq \frac{4V}{\pi^2} \cdot \frac{1}{(m+2)^2}$$

Recall:

• Continuity $\forall \varepsilon \exists \delta : |x-y| < \delta \Rightarrow |f(x) - f(y)| < \varepsilon$

• absolute continuity $\forall \varepsilon \exists \delta : \forall \text{ finite sequence of disjoint subintervals } (x_a, y_a)$

$$\sum_a |y_a - x_a| < \delta \Rightarrow \sum_a |f(y_a) - f(x_a)| < \varepsilon.$$

• Total variation

$$V_a^b(f) = \sup_P \sum |f(x_{i+1}) - f(x_i)|$$

partition of $[a, b]$, $P = \{x_0, \dots, x_m\}$

$$V_a^b(f) = \int_a^b |f'| dx \text{ if } f \text{ is differentiable}$$



↓ a measure of the length of a curve
(usually, we measure the length L)

$$\int_a^b \sqrt{1+(y')^2} dx$$

continuous diff

⇒ Lipschitz continuous \Rightarrow absolutely continuous \Rightarrow bounded variation

Chebfan

- divide interval into subintervals
- on each subinterval \rightarrow determine p_m such that
- use Chebyshev interpolant of degree m

$$\|f - p_m\|_\infty \approx \varepsilon_m$$

$m \log(m)$ ops.
FFT

→ work with p_m instead of f

variable chebfan \rightarrow store $\begin{cases} \text{- subintervals} \\ \text{- degrees of } p_m \\ \text{- coefficients of Cheb. projection} \end{cases}$

(11)

$$f(x) = \sum_{k=0}^{\infty} a_k T_k(x), \quad p_m(x) = \sum_{k=0}^m c_k T_k(x)$$

$f(x) = \sum_{k=0}^{\infty} a_k T_k(x)$

[Trig. 4.2] $\hookrightarrow = ?$

Theorem. Let f be Lipschitz continuous on $[-1, 1]$, $m \geq 1$. Then

$$\left\{ \begin{array}{l} c_0 = a_0 + a_{2m} + a_{4m} + \dots \\ c_k = a_k + (a_{k+2m} + a_{k+4m} + \dots) \\ \quad + (a_{-k+2m} + a_{-k+4m} + \dots) \\ c_m = a_m + a_{3m} + a_{5m} + \dots \end{array} \right.$$

$m=0 \quad m=1$

$k = 1, \dots, m-1$

\Rightarrow coefficients are all even of f

Proof.

- Realise, f has a unique Cheb. series, converges absolutely
 \Rightarrow we can rearrange the terms without affecting conv
- c_0, \dots, c_m are well-defined, the corresponding series in (*) converges
- $c_0 = \sum_{i=0}^{\infty} a_{2mi} = \sum_{i=0}^{\infty} a_{2mi} T_{2mi}(x)$, similarly the other coeff
- At Chebyshev points $x_j = \cos\left(\frac{j\pi}{n}\right)$, $j=0, \dots, m-1 \rightarrow$ aliasing
 $T_m(x_j) = T_{(2m-j)m}(x_j) = T_{(2m-j)m}(x_j) = \dots$

so that
 $\sum_{k=0}^m c_k T_k(x_j)$
underbrace a pol. of degree at most m

$$\begin{aligned} \sum_{k=0}^m c_k T_k(x_j) &= [a_0 + a_{2m} + \dots] T_0(x_j) + \sum_{k=1}^{m-1} [a_k + \dots] T_k(x_j) + [a_m + a_{3m} + \dots] T_m(x_j) \\ &= \sum_{k=0}^m a_k T_k(x_j) = f(x_j). \end{aligned}$$

aliasing \rightarrow can change the index to the index of a coeff in brackets

$\Rightarrow \sum_{k=0}^m c_k T_k(x_j)$ is interpolant in Cheb points, unique = p_m \blacksquare

Note

$$p_m(x) = \sum_{k=0}^m c_k T_k(x) = \sum_{j=0}^m a_j T_j(x) + \sum_{m=1}^{\infty} \left(a_{2mm} T_0 + \sum_{k=1}^{m-1} (a_{2mm+k} + a_{2mm-k}) T_k \right. \\ \left. + a_{2mm-m} T_m \right)$$

(*) poslopnach
mindestens zwei
 T_j a sech. poslopnach

$$\sum_{j=m+1}^{\infty} a_j T_{T_{m(m+j)}} \text{ additional index}$$

$0 \leq m \leq n$

$$m = (j+m-1) \bmod 2m - (m-1)$$

hence

$$f - f_m = \sum_{j=m+1}^{\infty} a_j T_j(x)$$

$$f - p_m = \sum_{j=m+1}^{\infty} a_j (T_j(x) - T_{m(\text{err}, j)}(x))$$

Lipschitz
↓

$$\|f - f_m\|_{\infty} \leq \sum |a_j| < \infty \quad \text{absolutely convergent!}$$

$$\|f - p_m\|_{\infty} \leq 2 \sum_{m+1}^{\infty} |a_j| < \infty$$

The Lebesgue constant of the Cheb. projection

$$R_m : f \mapsto R_m f = \sum_{i=0}^m a_i T_i \quad \begin{array}{l} \rightarrow \text{linear operator,} \\ \text{projection} \\ (\{T_0, \dots, T_m\} \text{ form a basis of} \\ \text{polynomials}) \end{array}$$

It can be shown that

$$\|R_m\|_{\infty} = \frac{1}{2\pi} \int_{-\pi}^{\pi} \left| \frac{\sin((m+\frac{1}{2})\theta)}{\sin(\frac{\theta}{2})} \right| d\theta$$

↓ orthogonal
projection

(technical and) $\|R_m\|_{\infty} \leq \frac{4}{\pi^2} \log(m+1) + 3, \|R_m\|_{\infty} \geq \frac{4}{\pi^2} \log(m+1)$

↗ best polynomial
approx

In summary, we know that

$$\|f - f_m\|_{\infty} \leq \left(4 + \frac{4}{\pi^2} \log(m+1)\right) \|f - p_m^*\|_{\infty} \rightarrow$$

$$\|f - p_m\|_{\infty} \leq \left(2 + \frac{2}{\pi} \log(m+1)\right) \|f - p_m^*\|_{\infty}.$$

* Note → linear projections
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Convergence

recall $LC \Rightarrow AC \Rightarrow BV$

Theorem $\forall v \geq 0$... integer. Let f and its derivatives through $f^{(v)}$ be absolutely continuous on $[-1, 1]$ and suppose the v^{th} derivative $f^{(v)}$ is of bounded variation V . Then for $k \geq m$, the Chebyshev coeffs. of f satisfy $|a_k| \leq V$.

$$|a_k| \leq \frac{2V}{\pi k(k-1)\cdots(k-v)} = \frac{2V}{\pi(k-v)^{v+1}}. \quad \text{open set}$$

If f is analytic with $|f(x)| \leq M$ in the region bounded by the ellipse with foci ± 1 and major and minor semiaxis lengths summing to $g > 1$, then $|a_k| \leq \frac{2M}{g^k} \rightarrow$ [Borwein 1912]

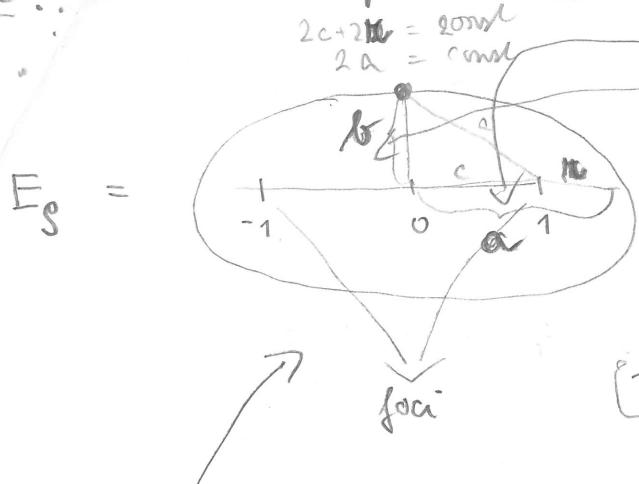
$$|a_0| \leq M, \quad |a_k| \leq \frac{2M}{g^k}.$$

Proof Book Trefethen

Thm 7.1 using complex analysis
Thm 8.1

Paper Ref. 2008 → standard real anal.
→ use integral representation of a_k and integration by part

Note: Bernstein ellipses $c+a=a$



differential pology

semi-major axes

semi-minor

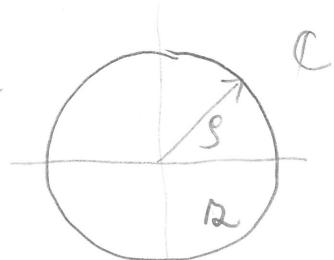
e ... linear eccentricity eccentricity

$$c=1$$

$$a^2 - b^2 = 1$$

$$\text{Define } g = a+b$$

[Bernstein 1912]



images of the circle of radius g in \mathbb{C} under the Joukowski map $x = \frac{1}{2}(a+a^*)$.

Theorem With the notation and assumptions of the previous theorem, it holds that for any $m > v$

$$\|f - f_m\|_\infty \leq \frac{2v}{\pi v(m-v)^v}, \quad \sim \frac{1}{m^v} \text{ provided } m$$

$$\|f - p_m\|_\infty \leq \frac{4v}{\pi v(m-v)^v}.$$

If f is analytic with $|f(x)| \leq M$ in the open region bounded by E_g , then

$$\|f - f_m\|_\infty \leq \frac{2Mg^{-m}}{g-1}, \quad \|f - p_m\|_\infty \leq \frac{4Mg^{-m}}{(g-1)}.$$

Proof: Follows from

$$\|f - f_m\|_\infty \leq \sum_{k=m+1}^{\infty} |a_k|, \quad \|f - p_m\|_\infty \leq 2 \sum_{k=m+1}^{\infty} |a_k|,$$

and bounding and summing $|a_k|$ of previous Theorems. \blacksquare

Note: If $f \in C[-1, 1]$ is analytic, it can be analytically continued to a neighborhood of $[-1, 1]$ in the complex plane. The bigger the neighborhood, the faster the convergence.

$$\text{E.g. } \sum_{k=m+1}^{\infty} \frac{1}{(k-v)^{v+1}} \leq \int_v^{\infty} \frac{1}{(x-v)^{v+1}} dx = \frac{1}{v(m-v)^v}$$

$$\sum_{k=m+1}^{\infty} \frac{2M}{g^k} = 2M \int_0^{g-(m+1)} \sum_{j=0}^{\infty} g^{-j-1} = 2M \frac{g^{-(m+1)}}{1-g^{-1}} = 2M \frac{g^{-m}}{g-1}$$



area

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(To see connections)

Note It can be shown the following theorem [Powell 17.4, p. 208] (14).

Theorem If L is any bounded linear operator from $C[-1, 1]$ to P_m that satisfies the projection condition $Lp = p \forall p \in P_m$, then the inequality

$$\|L\|_{\infty} \geq \frac{1}{2} \|R_0 + R_m\|_{\infty} \text{ holds.}$$

$$\|R_0\|_{\infty} = 1$$

$$\Rightarrow \|L\|_{\infty} \geq \frac{2}{\pi^2} \ln(m+1) - \frac{1}{2}$$

Notes on computation

- evaluate f at Cheb. point $\cos\left(\frac{k\pi}{m}\right)$

- evaluate Cheb. interp in $O(n)$ op.

- need to compute a_k ... coefs of Cheb projection

control accuracy

manipulate with f work

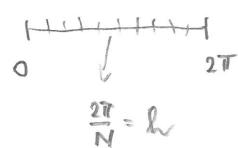
$$\frac{2}{\pi} \int_{-1}^1 f(T_k(x)) \frac{dx}{\sqrt{1-x^2}} = \frac{2}{\pi} \int_0^\pi f(\cos\theta) \cos(k\theta) d\theta = \frac{1}{\pi} \int_{-\pi}^\pi f(\cos\theta) \cos(k\theta) d\theta$$

$$x = \cos\theta \\ d\theta = -\frac{dx}{\sqrt{1-x^2}}$$

$$\begin{aligned} & \text{cos is symmetric} \\ & = \frac{1}{\pi} \int_0^{2\pi} f(\cos\theta) \cos(k\theta) d\theta \\ & \text{periodic} \\ & \text{standard form.} \end{aligned}$$

N ... powers of 2

$$\frac{1}{\pi} \int_0^{2\pi} f(\theta) d\theta \approx \frac{1}{\pi} \sum_{k=0}^{N-1} f\left(\frac{2k\pi}{N}\right) \frac{2\pi}{N} = \frac{2}{N} \sum_{k=0}^{N-1} f\left(\frac{2k\pi}{N}\right)$$



$$a_{k_0} \approx \frac{2}{N} \sum_{k=0}^{N-1} f\left(\cos\left(\frac{2k\pi}{N}\right)\right) \cdot \cos\left(k\frac{2\pi}{N}\right) = \frac{2}{N} \langle \vec{f}, \vec{c}_{k_0} \rangle$$

→ Discrete cosine basis

$$\begin{bmatrix} a_0 \\ \vdots \\ a_{k_0} \end{bmatrix} \approx \frac{2}{N} \begin{bmatrix} -\vec{c}_0 \\ \vdots \\ -\vec{c}_{k_0} \end{bmatrix} \begin{bmatrix} \vec{f} \\ \vdots \\ \vec{f} \end{bmatrix}$$

choose
 $k_0 = N-1$

$$N = 2^{\log_2 m}$$

can be computed using FFT.

$\rightarrow N \log N$ op

$$\sum_{k=0}^m c_k F_k(x) \xrightarrow{3 \text{ term recursive}} O(n) \text{ op.}$$

• We can evaluate f_m using CLENSHAW'S Algorithm.

• solving nonlinear equations

$$f \leftrightarrow f_m, \text{ solve } f_m(x) = 0$$

→ polynomial represented in basis T_i

$$f_m(x) = \sum_{k=0}^m a_k T_k(x)$$

$f_m(x)$ is characteristic polynomial of \rightarrow switch to each nodes
and minimal

$$C = \begin{bmatrix} 0 & 1 & & \\ -\frac{1}{2} & \frac{1}{2} & & \\ & & \ddots & \\ & & & \frac{1}{2} \end{bmatrix} - \frac{1}{2a_m} \begin{bmatrix} 0 & & & \\ 1 & 0 & & \\ & 0 & \ddots & \\ & & & a_0 a_1 \dots a_{m-1} \end{bmatrix} \rightarrow \boxed{\text{Colleague matrix}} \rightarrow \text{just eigenvalue computation}$$

Recall if $q(x) = \sum_{k=0}^n q_k x^k \rightarrow$ is char & min pol. of

$$\begin{bmatrix} 0 & & & \\ -a_0 & 1 & & \\ & & \ddots & \\ & & & 1-a_{m-1} \end{bmatrix} = \begin{bmatrix} 0 & & & \\ 1 & & & \\ & \ddots & & \\ & & 1 & 0 \end{bmatrix} - \begin{bmatrix} 0 & & & \\ 1 & 0 & & \\ & 0 & \ddots & \\ & & & a_{m-1} \end{bmatrix} \rightarrow \boxed{\text{Companion matrix}}$$

• integrating

$$\int_{-1}^1 f(x) dx \approx \int_{-1}^1 p_m(x) dx$$

✓ if $p_m = \sum_{k=0}^m c_k T_k$, show

~ GQ
weighting wj
rule daly

→ to be interpolating quadrature rule
→ Clenshaw-Curtis quadrature

we know how
to get c_k
from a_k .

$$\int_{-1}^1 p_m(x) dx = \sum_{k=0}^m a_k \underbrace{\int_{-1}^1 T_k(x) dx}_{\substack{0 \text{ for } k \text{ odd} \\ 2 \text{ for } k \text{ even}}} = 2 \sum_{k=0}^m \frac{c_k}{1-k^2}$$

1. Koeficieny
2. Vyhodnoceni Σ
3. Konec
4. Integrace

Proof

Consider

$$N(x) = \begin{bmatrix} T_0(x) \\ \vdots \\ T_{m-1}(x) \end{bmatrix}$$

$$T_0(x) = 1 \quad T_1(x) = x$$

$$T_{a+1}(x) = 2 \times T_a(x) - T_{a-1}(x)$$

$$\mathcal{L} N(x) = \begin{bmatrix} T_1(x) \\ \frac{1}{2} T_0(x) + \frac{1}{2} T_2(x) \\ \vdots \\ \frac{1}{2} T_{m-3}(x) + \frac{1}{2} T_{m-1}(x) \\ \frac{1}{2} T_{m-2} - \frac{1}{2a_m} \sum_{a=0}^{m-1} a \alpha_a T_a \\ \uparrow \\ \pm \frac{1}{2} T_m(x) \end{bmatrix} = \begin{bmatrix} x T_0 \\ \vdots \\ x T_{m-2} \\ x T_{m-1}(x) - \frac{1}{2a_m} \underbrace{\sum_{a=0}^m a \alpha_a T_a}_{f_m(x)} \\ \downarrow \\ x N(x) - \frac{1}{2a_m} \begin{bmatrix} 0 \\ \vdots \\ 0 \\ f_m(x) \end{bmatrix} \end{bmatrix}$$

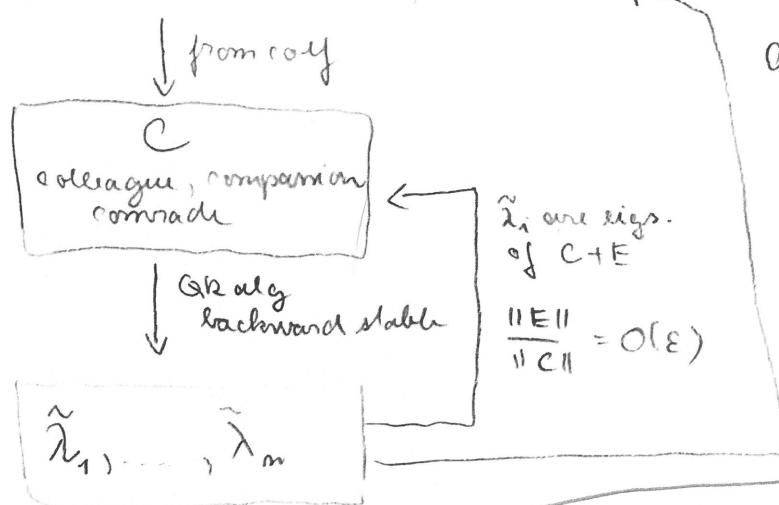
- x is root of $f_m(x) \Rightarrow x$ is an eigenvalue of \mathcal{L}
- if f_m has m distinct roots \Rightarrow they are precisely the eigs. of \mathcal{L}
- if f_m has multiple roots \rightarrow consider small perturbations of coeff so that the roots become distinct

$$\tilde{f}_m \leftrightarrow \tilde{\mathcal{L}}$$

Roots of polynomials as well as eigenvalues of \mathcal{L} are continuous functions of coeff \rightarrow multiplicities must be preserved in the limit as perturbations $\rightarrow 0$.

Remark about numerical stability of computation of roots

$$q(x) = Y_m(x) + \sum_{a=0}^{m-1} a \alpha_a Y_a(x) \quad Y_i \dots \text{basis}$$



Are $\tilde{\lambda}_i$ roots of a
nearly polynomial \tilde{q} ?
Denote $\|g\| = \sqrt{\sum_{a=0}^{m-1} a^2 \alpha_a^2}$
It holds that

$$\frac{\|\tilde{q} - q\|}{\|q\|} = O(\varepsilon) \|g\|$$

if this is big,

holds for monomial & cheb. basis

the computation of roots need not be backward stable.

Problem formulation

- $p(x) = \sum a_i x^i$
- $q(x) = \sum b_i T_i$
- generate randomly a_i, b_i
- Where are the roots placed?

The Perfidious Polynomial

Wilkinson's polynomial, paper 1970

$$p(x) = a_0 + a_1 x + \cdots + a_{19} x^{19} + x^{20} = \prod_{k=1}^{20} (x - k)$$

$$\tilde{p}(x) \equiv \tilde{a}_0 + \tilde{a}_1 x + \cdots + \tilde{a}_{19} x^{19} + x^{20}$$

