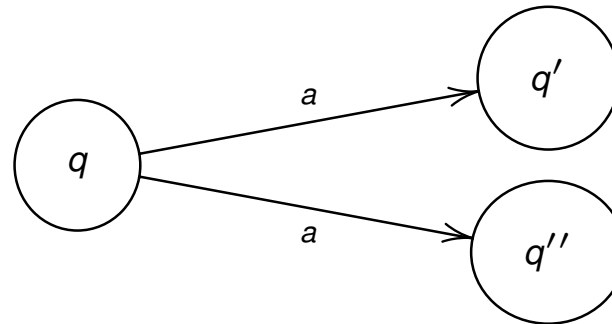


## 2.4 Nondeterministic Finite-State Automaton



### Definition 2.14

A *nondeterministic finite-state automaton* (NFA)  $A$  is given through a 5-tuple  $(Q, \Sigma, \delta, S, F)$ , where

- $Q$  is a finite set of (internal) *states*,
- $\Sigma$  is a finite (input) *alphabet*,
- $Q \cap \Sigma = \emptyset$ ,
- $S \subseteq Q$  is a set of *initial states*,
- $F \subseteq Q$  is a set of *final states*, and
- $\delta : Q \times \Sigma \rightarrow 2^Q$  is a *transition relation*.

An NFA can be described by a *state graph* just like a DFA.

## Definition 2.14 (cont.)

Let  $A = (Q, \Sigma, \delta, S, F)$  be an NFA.

The transition relation  $\delta$  is extended to a **function**  $\hat{\delta}: 2^Q \times \Sigma^* \rightarrow 2^Q$ :

$$\hat{\delta}(P, \varepsilon) := P \text{ for all } P \subseteq Q,$$

$$\hat{\delta}(P, ax) := \bigcup_{q \in P} \hat{\delta}(\delta(q, a), x) \text{ for all } P \subseteq Q, a \in \Sigma, \text{ and } x \in \Sigma^*.$$

$L(A) := \{ x \in \Sigma^* \mid \hat{\delta}(S, x) \cap F \neq \emptyset \}$  is the **language accepted by  $A$** .

## Remark

$$\hat{\delta}(S, a_1 a_2 \dots a_n) \cap F \neq \emptyset$$

iff

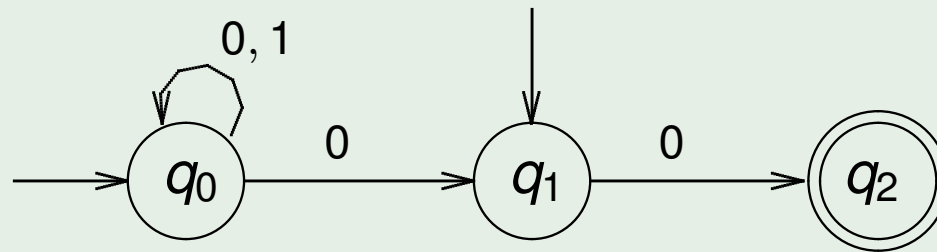
$$\exists q_0, q_1, \dots, q_n \in Q : q_0 \in S \wedge q_n \in F \wedge q_i \in \delta(q_{i-1}, a_i) \quad (1 \leq i \leq n).$$

iff

$\exists q_0 \in S \exists q_n \in F$  : In the state graph of  $A$ ,  
there is a directed path from  $q_0$  to  $q_n$  with label  $a_1 a_2 \dots a_n$ .

## Example:

(a)  $A_1$ :



Let  $x := 1100$ . Then:

$$S = \{q_0, q_1\} \xrightarrow{1} \{q_0\} \xrightarrow{1} \{q_0\} \xrightarrow{0} \{q_0, q_1\} \xrightarrow{0} \{q_0, q_1, q_2\}$$

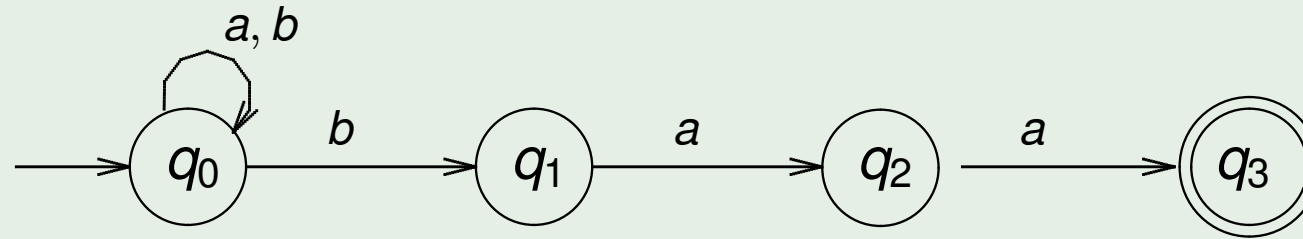
Hence,  $x \in L(A_1)$ .

In fact:

$$L(A_1) = \{ x \in \{0, 1\}^* \mid x = 0 \text{ or } \exists y \in \{0, 1\}^* : x = y00 \}.$$

## Example (cont.):

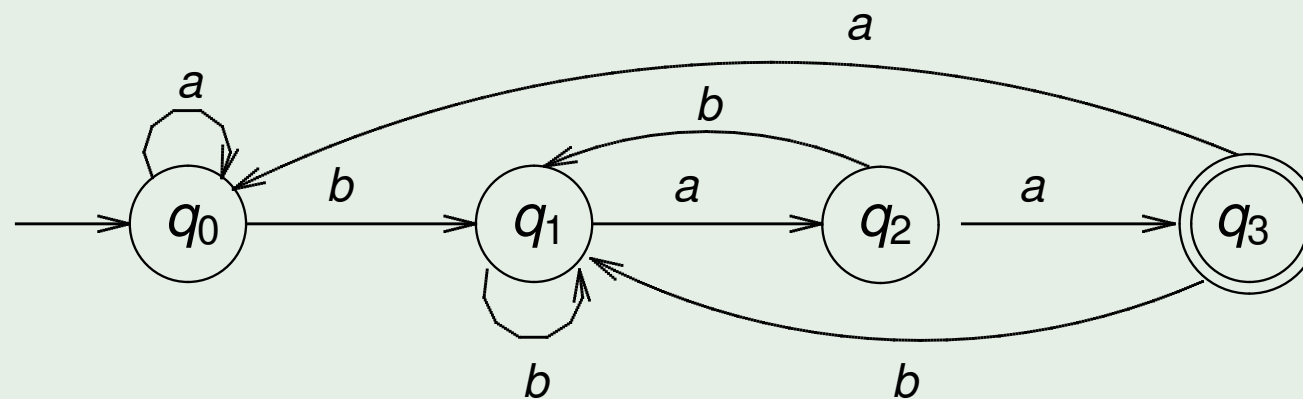
(b)  $A_2$ :



$$L(A_2) = \{ w \in \{a, b\}^* \mid w \text{ has suffix } baa \}.$$

A DFA for this language:

$A_3$ :



## Theorem 2.15 (Rabin, Scott)

*From an NFA  $A$ , a DFA  $B$  can be constructed such that  $L(B) = L(A)$ .*

### Proof.

Let  $A = (Q, \Sigma, \delta_A, S, F)$  be an NFA.

**Goal:** A DFA  $B = (P, \Sigma, \delta_B, p_0, G)$  such that  $L(B) = L(A)$ .

**Power set construction:**

$$P := 2^Q, p_0 := S,$$

$$G := \{ Q' \subseteq Q \mid Q' \cap F \neq \emptyset \},$$

$$\delta_B(Q', a) := \bigcup_{q \in Q'} \delta_A(q, a) = \hat{\delta}_A(Q', a)$$

for all  $Q' \subseteq Q$  and all  $a \in \Sigma$ .

## Proof of Theorem 2.15 (cont.)

Claim:

$$L(B) = L(A).$$

Proof.

$$\varepsilon \in L(A) \text{ iff } S \cap F \neq \emptyset \text{ iff } S \in G \text{ iff } \varepsilon \in L(B).$$

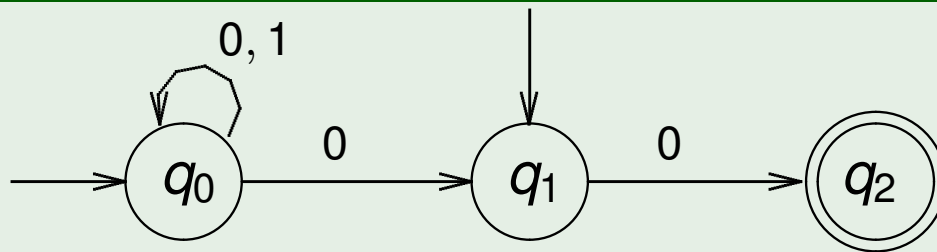
Now let  $x = a_1 a_2 \dots a_n \in \Sigma^+$ .

$$\begin{aligned} \text{Then: } x \in L(A) &\text{ iff } \hat{\delta}_A(S, x) \cap F \neq \emptyset \\ &\text{ iff } \exists Q_1, Q_2, \dots, Q_n \subseteq Q : \delta_B(S, a_1) = Q_1, \\ &\quad \delta_B(Q_1, a_2) = Q_2, \dots, \delta_B(Q_{n-1}, a_n) = Q_n \text{ and } Q_n \cap F \neq \emptyset \\ &\text{ iff } \hat{\delta}_B(S, x) \in G \text{ iff } x \in L(B). \end{aligned}$$

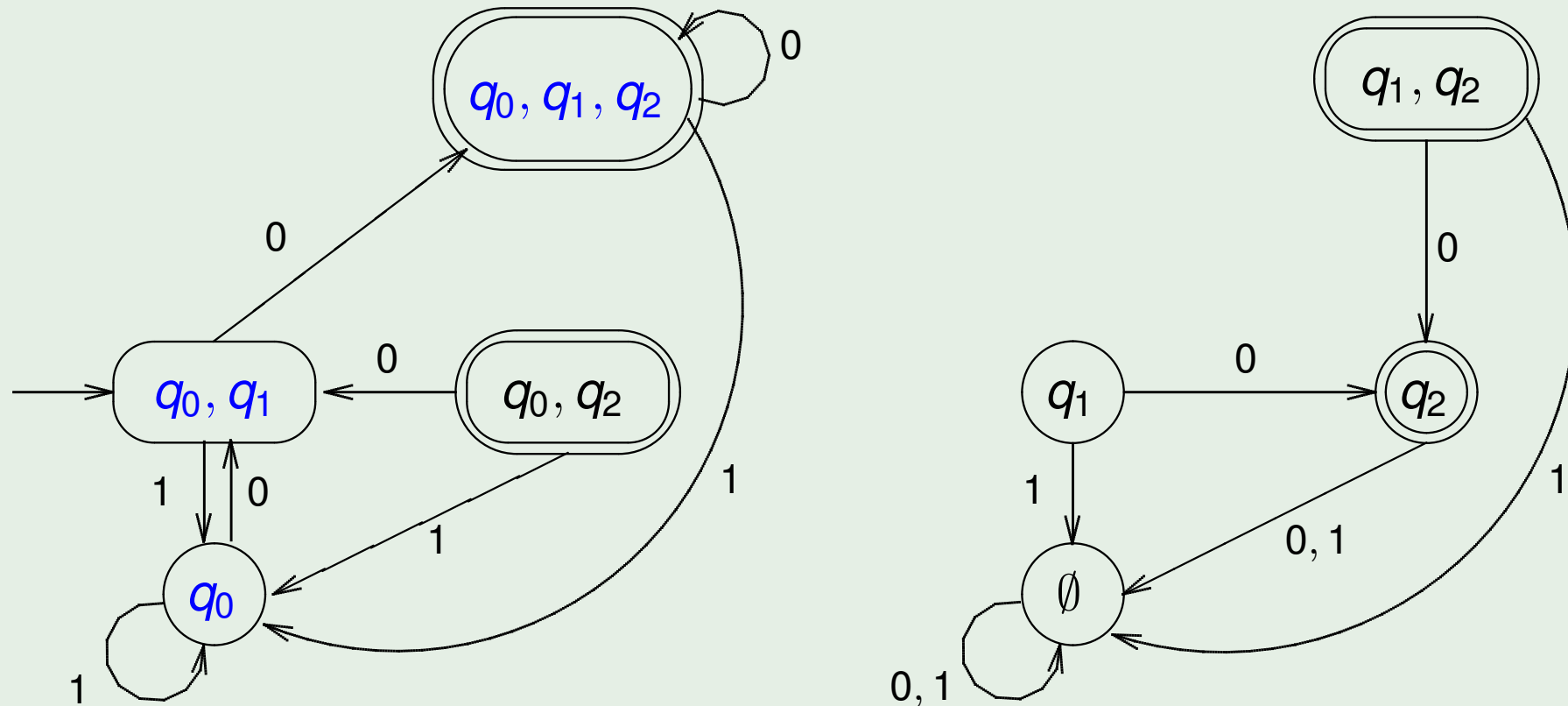
□ □

## Example (cont.):

A:



B:



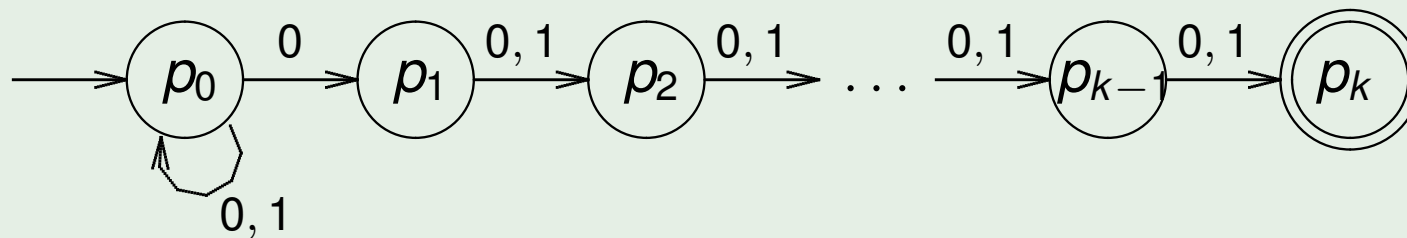
## Remark

Only compute the subautomaton of  $B$  that is reachable from  $S$ !

## Example:

$$L_k := \{ x = x_1 \dots x_n \in \{0, 1\}^* \mid |x| = n \geq k \text{ and } x_{n-k+1} = 0 \}$$

An NFA  $A_k$  with  $L(A_k) = L_k$ :



Let  $B = (Q, \{0, 1\}, \delta, q_0, F)$  be a DFA such that  $L(B) = L_k$ .



## Example (cont.):

**Claim:**  $|Q| \geq 2^k$ .

### Proof.

Assume that  $Q = \{q_0, q_1, \dots, q_r\}$ , where  $r < 2^k - 1$ .

Then:  $\exists y_1, y_2 \in \{0, 1\}^k : y_1 \neq y_2$  and  $\hat{\delta}(q_0, y_1) = \hat{\delta}(q_0, y_2)$ .

Let  $i$  be the leftmost position such that  $y_1(i) \neq y_2(i)$ ,  
w.l.o.g.  $y_1 = u0v_1$  and  $y_2 = u1v_2$ .

Let  $w \in \{0, 1\}^{i-1}$  be arbitrary.

Then:  $y_1 w = u0v_1 w$ ,  $|v_1 w| = k - i + i - 1 = k - 1$

$\leadsto y_1 w \in L_k$

$y_2 w = u1v_2 w$ ,  $|v_2 w| = k - 1$

$\leadsto y_2 w \notin L_k$ .

But:  $\hat{\delta}(q_0, y_1 w) = \hat{\delta}(\hat{\delta}(q_0, y_1), w)$   
 $= \hat{\delta}(\hat{\delta}(q_0, y_2), w)$   
 $= \hat{\delta}(q_0, y_2 w)$ , a **contradiction!**

□